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(54) Title: SOLID-STATE RAM DATA STORAGE FOR VIRTUAL MEMORY COMPUTER USING FIXED-SIZE SWAP PAGES <div data-bbox="354 1071 1258 1495"> </div>		
(57) Abstract <p>A computer using virtual memory management employs a random-access type storage device such as a semiconductor memory for page swapping. The semiconductor memory is formatted to provide multiple partitions of varying block size, e.g., two block sizes, for compressed pages, and another block size for uncompressed original-sized pages. The data to be stored is in pages of fixed size, and these pages are compressed for storage if the compressed size fits in the block size of one of the small-block partitions in the memory. If a data page is not compressible to one of the small block sizes, it is stored uncompressed in the other full-size partition. The operating system maintains a table storing the locations of the pages in the partitions, so upon recall the page (if compressed) is retrieved from its location found using the table, decompressed and sent to the CPU. The relative number of blocks in the partitioned memory (e.g., the physical storage capacity of the memory) is set (or dynamically allocated) at the average ratio of compressible pages to uncompressible pages for the compression algorithm used. For example, an algorithm may compress 90 % of the pages to either 50 % or 70 % of their original size, so a ratio of the number of locations in the compressed partitions of the semiconductor memory to the number of locations in the uncompressed partition is selected as 90:10. The compression mechanism operates on bytes in bit parallel format, and uses a lookahead buffer which is compared with bytes in a window to produce 9-bit symbols. The stream of 9-bit symbols passes through an ECC generator, also operating in bit-parallel.</p>		

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10 **SOLID-STATE RAM DATA STORAGE FOR VIRTUAL MEMORY**
 COMPUTER USING FIXED-SIZE SWAP PAGES

15 This application is in part a continuation of copending application Serial
No. 627,722, filed December 14, 1990, by William D. Miller, Gary L.
Harrington and Lawrence M. Fullerton, for "Storage of Compressed Data on
Random Access Storage Devices", assigned to CERAM, Inc., the assignee of
the present application.

20 This invention relates to digital data storage and retrieval, and more
particularly to page-oriented storing of compressed or uncompressed data in
randomly-accessed locations of fixed sizes in partitioned storage devices. The
invention is particularly adapted for storing fixed-size pages swapped with main
memory in a computer system using a virtual memory management scheme.

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 A computer implementing a virtual memory system typically employs a
certain amount of "physical" memory composed of relatively fast semiconductor
RAM devices, along with a much larger amount of "virtual" memory composed
of hard disk, where the access time of the hard disk is perhaps several hundred
30 times that of the RAM devices. The physical memory or "main memory" in a
virtual memory system is addressed as words, while the virtual "disk memory" is
addressed as pages. The virtual memory management scheme uses an
operating system such as UNIXTM along with hardware including a translation
buffer, as is well known. In multi-tasking operation where more than one

program runs at the same time, each running in a time slice of its own, each program appears to have an entire memory space to itself. To make room in the physical memory to run a new program, or to allocate more memory for an already-running program, the memory management mechanism either "swaps" out an entire program (process) to disk memory or "pages" out a portion (page) of an existing process to disk. A typical page size is 4Kbytes.

Transferring data to and from disk memory is very slow compared to the transfer time to main memory, and so "solid state disks" (composed of semiconductor RAMs like the main memory) have been used as a substitute for magnetic disk to improve system performance. This is at a much higher cost per megabyte of storage, however, due to the cost of semiconductor RAMs. Data compression has not been used because of the variable-length record problem as discussed below, i.e., compressed data blocks are of variable size, making random access of compressed "pages" of data impractical.

As explained in application Serial No. 627,722, data compression encoding algorithms are commonly applied to data which is to be archived or stored at the tertiary storage level. In a hierarchy of data storage, a RAM directly accessed by a CPU is often referred to as the primary level, the hard disk as the secondary level, and tape (back up) as the tertiary level. The characteristic of tertiary level storage as commonly implemented which supports use of compression is that the data access is largely sequential. Data is stored in variable-length units, sequentially, without boundaries or constraints on the number of bytes or words in a storage unit. Thus, if a file or page being stored compresses to some arbitrary number of bytes this can be stored as such, without unused memory due to fixed sizes of storage units. Compression can be easily applied in any such case where the data is not randomly accessed but instead is sequentially accessed. For this reason, data compression works well for data streaming devices such as magnetic tape. It

has been applied to databases holding very large records on magnetic and optical disks.

Data compression is not readily adaptable for use with random access storage devices such as hard disks or solid-state disks, although in many cases it would be desirable to do so. The reason for this lack of use of data compression is that algorithms for data compression produce compressed data units which are of variable size. Blocks of data of fixed size compress to differing sizes depending upon the patterns of characters in the blocks; data with large numbers of repeating patterns compress to a greater degree than a more random distribution of characters. Text files and spreadsheet files compress to smaller units than executable code or graphics files. This problem of variable-length records has made random access of compressed data records, as managed by operating systems and controllers in computer systems, impractical.

It is the principal object of this invention to provide a low-cost, high-speed, semiconductor memory device useful in a computer implementing page swapping, as required in virtual memory computer architecture, particularly a device employing data compression to reduce cost, and using error detecting and correcting techniques to increase reliability. Another object is to provide an improved method of storing data in a computer system or the like, and particularly to provide a method of compressing data pages for storage in a storage medium having an access capability for storing data units of fixed size. Another object is to provide an improved data compression arrangement using a random-access type of storage device, where the data units to be stored and recalled are of fixed length and the storage device is accessed in fixed-length increments, where the length is small enough for this to be considered random access of data. A further object is to reduce the amount of unused storage space in a storage device when compressed data units are stored, and therefore

increase the storage density. An additional object is to provide an improvement in the cost per byte of storage capacity in a storage device.

In accordance with one embodiment of the invention, a solid-state
5 memory unit for page-swap storage employs data compression in which
compressed data partitions are provided in DRAM memory for at least two
different compressed data sizes. Data that will not compress to the block sizes
specified for compressed data is stored uncompressed, in another partition in
the DRAM memory, for example. As set for in application Serial No. 627,722,
10 a storage arrangement for compressed data may advantageously use multiple
partitions, where each partition is a section of available physical storage space
having an address known to the system which differentiates it from other
partitions. The data to be stored is in blocks, i.e., units of data of some fixed
size, as distinguished from byte or word oriented data of variable length. The
15 partitions are capable of holding multiple blocks, each randomly accessible.
The data blocks may be compressed if the compressed size fits in the fixed
block size of one of the partitions in the storage device. To accommodate data
which is compressible to a varying degree, yet avoid waste of unused space in
the partitioned memory device, the partitions are made of differing block sizes;
20 for example, there may be two partitions, these two having block sizes
corresponding to the typical compressed sizes of the blocks of data. These
compressed sizes may be perhaps one-half and two-thirds the size of the
original data blocks in a typical situation. Data which cannot be compressed
to the two-thirds value or less is either stored in other storage (e.g., the hard
25 disk) or preferably is stored in a third partition of the memory device with
block size of the original (uncompressed) data. The storage arrangement may
preferably use a semiconductor RAM array, or it may use a combination of
RAM and disk as described in the application Serial No. 627,722.

30 In one embodiment, a data storage device, such as a bank of DRAMs,
is employed for storing all page-swap data for a virtual memory management

system. The semiconductor memory is partitioned into three parts, two of these for compressed pages and one for the small percentage of page that will not compress to a given size. The two fixed-size compressed block partitions are formatted for two different compressed block sizes equal to what a
5 compressed version of the original block size will fit into for the majority of cases. One of these partitions is for blocks 50% of the original size, and the other for 70% of original, in one example. The relative number of blocks in each partition (e.g., the physical storage capacity of each partition) is set at the average ratio of compressible blocks to uncompressible blocks for the
10 compression algorithm used. By compressible it is meant that the block of data can be compressed to the block size of one of the compressed block partitions, and by uncompressible it is meant that the block will not compress to the required block size to fit in the compressed block partition. It is reasonable to select an algorithm that will compress 90% of the blocks to
15 either 50% or 70% of their original size, so in this case a ratio of the number of blocks in the compressed partitions to the number of blocks in the uncompressed partition is selected as 90:10. The size of the blocks is selected to be some efficient value depending upon the system and the way data is handled in the system; for example, the block size is probably best selected to
20 be the page size of 4Kbytes, or a submultiple of the page size. Although the page size is typically 2K-bytes or 4K-bytes in the most commonly-used operating systems, other sizes may be appropriate. In the example embodiment, the block size of uncompressed data is selected to be 4Kbytes (actually 4096-bytes), while compression to 50% would mean one of the
25 compressed data block size is 2Kbytes (2048-bytes) and compression to 70% would mean the other block size is about 2.8-Kbytes. A hit rate of approximately 90% may be achieved with this partitioning. The 10% of pages found not compressible to the 70% size are stored uncompressed in the third partition of the DRAM memory.

30

In one embodiment, a method is provided for collecting statistics on the page data being handled, and adapts the partitions to optimize capacity based on the kind of data encountered. Thus, the partitioning is adaptive, changing according to the compressibility of the page data.

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In an alternative embodiment, instead of using the third partition of the DRAM memory, the ordinary storage device, such as a hard disk, is employed for pages that cannot be compressed to the threshold 70% size. The disk storage is used as uncompressed storage, functioning as a partition made up of
10 addressable locations of a block size equal to that of the original uncompressed data (e.g., page size of 4KB).

In operation of the preferred embodiment, the computer system sends (writes) data in blocks (pages) to the storage device, and before being written
15 the data blocks pass through a compression unit which attempts to compress the blocks using the algorithm of choice. A counter keeps track of how many bytes of physical storage are required to store the compressed data. If the number exceeds the size of the blocks used for physical data storage in the larger of the two compressed data partitions, then the actual amount of storage
20 required (value in the counter) is returned to the operating system, which resends the page to the correct partition, so the data block is written uncompressed in the other partition and the addressing information maintained by the operating system reflects this. But if the block is compressed to the number of bytes of the smallest compressed partition then
25 the data is stored in this compressed partition, or if compressed to the size of the larger compressed data partition it is stored thus, and in either event the location is recorded as such by driver software (added to the operating system). The driver records the values in the operating system kernel data structures which map the page-swap device translations. Upon recall, a
30 request from the computer for a given page is checked against these stored addresses, and retrieved from the partition where it is found, then, if necessary,

decompressed before sending to the computer. The average performance of the page swapping operation is greatly enhanced, the pages are stored in much faster semiconductor memory.

5 The performance of the page-swap memory unit as described will depend upon the speed of the compression and decompression mechanism. If the data compression requires too long, then the speed advantage of semiconductor RAMs over hard disk is lost. Therefore, in one embodiment, a compression arrangement is employed which operates upon one to four byte
10 segments of data and performs a single-clock compression of this data if a match is found. In particular, Lempel-Ziv compression circuitry is employed which performs comparisons of all match sizes of a lookahead buffer to all positions in a window, for single-clock compression of all matches (one to four bytes). A tuned Lempel-Ziv algorithm uses 8-bit symbols, with a 64-symbol
15 window, and a four-symbol lookahead buffer. This algorithm produces output values that are the same bit-width (9-bits) for either match or no-match to greatly simplify the task of bit-packing the compressed output. The DRAM storage for compressed data is arranged in a bit-width (36-bits) that is a multiple of the compressed data size (9-bits) to simplify the task of circuitry
20 which bit-packs the compressed output. This compression mechanism is pipelined so that one byte is passed every clock cycle.

 An important feature is the use of ECC (error correcting code) to maintain data integrity, even though DRAMs with potentially high soft error
25 rates are employed. That is, the DRAMs may have soft error rates which are not acceptable for use in main memory, and may indeed be slower than ordinarily used for DRAM storage and have other relaxed specifications; these devices are referred to as "audio grade" DRAMs by some in the industry. The data being stored in the memory unit (whether compressed or uncompressed)
30 passes through an ECC generator circuit to produce a code that is stored with each block of bytes, then upon recall the ECC circuit checks the code and

makes a correction if a recoverable error is detected. The ECC logic uses a BCH code with a 9-bit character size to effectively correct errors on the 9-bit compressed data.

5 Another feature of the invention is the use of high-performance DMA interface to the system bus. A FIFO is included to buffer write data coming into the compression unit or read data going from the compression unit to the system bus, and when a bus grant is received a burst of data is sent instead of just one word. In the interface between the memory controller and the
10 DRAM memory, a 2-word buffer is employed so that a page-mode read or write can be implemented if two words are waiting to be accessed.

 The novel features believed characteristic of the invention are set forth in the appended claims. The invention itself, however, as well as other
15 features and advantages thereof, will be best understood by reference to the detailed description of specific embodiments which follows, when read in conjunction with the accompanying drawings, wherein:

 Figure 1 is an electrical diagram in block form of a digital system
20 including a memory for storing pages of data, using features of one embodiment of the invention;

 Figure 2 is a more detailed electrical diagram in block form of a data
25 compression unit and ECC unit used in the system of Figure 1.

 Figure 3 is a more detailed electrical diagram of the compression and decompression circuits in the system of Figure 2;

 Figure 4 is a diagram of the contents of the lookahead buffer and
30 window buffer in the circuit of Figure 3 for an example of a data input;

Figure 5 is an electrical diagram of the ECC encoder circuit 45 of Figure 2;

Figure 6 is a diagram of the code word structure at the output of the ECC encoder circuit of Figure 5;

Figure 7 is an electrical diagram of a bit serial encoder used for explaining the function of the circuit of Figure 5;

Figure 8 is an electrical diagram of another bit serial encoder used for explaining the function of the circuit of Figure 5;

Figure 9 is an electrical diagram of an ECC decoder circuit 46 used in the system of Figure 2;

Figure 10 is an electrical diagram of a circuit for computing a partial syndrome as used in the circuit of Figure 9;

Figure 11 is an electrical diagram of a bit-serial S_1 -calculator used in the circuit of Figure 9;

Figure 12 is an electrical diagram of a symbol-wide S_1 -calculator used in the circuit of Figure 9;

Figure 13 is an electrical diagram of a bit-serial S_3 -calculator used in the circuit of Figure 9;

Figure 14 is an electrical diagram of a symbol-wide S_3 -calculator used in the circuit of Figure 9;

Figure 15 is an electrical diagram of an ECC error corrector circuit used in the system of Figure 9;

5 Figure 16 is an electrical diagram of a mapper circuit used in the error corrector circuit of Figure 15;

Figure 17 is an electrical diagram of an equality detector circuit used in the circuit of Figure 16;

10 Figure 18 is an electrical diagram of an error detection logic circuit used in the circuit of Figure 16;

Figure 19 is a diagram of the mapping of memory 17 in accordance with a dynamic allocation method, according to one embodiment; and
15

Figure 20 is another diagram of mapping the memory 17 in accordance with the dynamic allocation method.

Referring to Figure 1, a data compression method according to the
20 invention is used in a system having a source 10 of data to be stored and recalled, and in a typical application this source would be a CPU or the like, although various other data sources may use the features herein disclosed. In particular, the data source 10 is the CPU of a workstation or the like, using a virtual memory management scheme such as the UNIX operating system
25 handling fixed-size pages of data (e.g., each page is 4Kbyte). The CPU 10 employs a main memory 11 coupled to the CPU by a system bus 12, and secondary storage 13 is also coupled to the CPU by the bus 12. When the CPU 10 has a unit of data to store it is sent by the bus 12 along with appropriate addresses and controls in the usual manner of operating a CPU
30 with main memory and disk storage or the like. When the unit is a page to be swapped, however, as when the CPU 10 is executing an operating system using

virtual memory, the page is written to a swap space in secondary storage 13 (this secondary storage constructed according to the invention taking the place of what is usually simply a hard disk in conventional systems). The secondary storage includes a disk 14 operated by a disk controller 15 for storing files in the usual manner (and also for storing uncompressed fixed-size page data in an alternative embodiment). In addition, a swap space or swap partition is provided, as is usual for UNIX virtual memory management, and according to a preferred embodiment this swap space uses a data compression unit 16 along with a DRAM memory 17 for storing compressed pages. The data compression mechanism 16 examines each page of data received from the CPU 10 during a page-swap operation and determines whether or not compression is possible for this page. If compression is elected, the compression mechanism 16 sends the compressed page of data to the memory 17. The memory 17 contains three storage areas 18, 19 and 20 for two fixed sizes of compressed page-oriented storage and one size of uncompressed storage. The area 18 is of a size for 50% compression and the area 19 for 70% compression, while the area 20 is for uncompressed pages. If a page can be compressed to 70% or less of its original 4Kbyte size in the compression unit 16, then the compressed page of data is sent to the memory 17 to be stored in the area 18 or area 19, depending upon the degree of compression. On the other hand, if compression to 70% or less is not possible, the page is stored in the uncompressed area 20 in a preferred embodiment; alternatively, a partition in the disk 14 reserved for page swapping, i.e., for virtual memory management, may be used for these uncompressed pages. The operating system maintains a table indexed by virtual page address giving the location of each page, i.e., whether it is present in memory 11, or, if not, which partition in swap space it is located in.

In the example embodiment, using 4Kbyte page size, and employing 32-bit (4-byte) word width and data bus width in the bus 12, a page is transferred on the bus 12 as a 1K-word block of data, using a page address (low-order 12-

bits of byte address is all zeros). If compressed to 50%, this 1Kword block would be stored in the memory partition 18 in approximately a 512-word block (the bits added by the ECC circuitry would add to the size). If compressed to 70%, the 1Kword block would be stored in the memory partition 19 in about a 700-word block. If not compressible, it is stored in partition 20 as a 1024-word block (plus ECC increment added). The ratio of sizes of the partitions 18, 19 and 20 may be selected based upon historical empirical data of the compressibility of the data for the particular code and data in the task being executed. Or, the partitioning may be dynamically altered depending upon the actual compressibility of the currently executing task. In either event, the partition 20 is of a size needed to store only about 10% of the pages.

The operating system executed by the computer 10 maintains a table in memory 11 of the locations of pages. As each page is stored in the memory 17, its location is returned to the operating system. Or, if a page is present in physical memory, this is indicated in the page tables. When a memory reference is made by the CPU to data in a page not present in physical memory, then a page fault is executed, resulting in a page swap. Various algorithms may be used to decide which page to swap out to make room for the needed page in physical memory. An alternative way of operating the page swap mechanism of the invention is to mark the uncompressible pages to be always present in physical memory, rather than storing them in the partition 20, in which case there is no need for the partition 20.

In another alternative embodiment, if the hard disk 14 were used for uncompressed storage, the mapping of page location could be maintained by the secondary storage itself, rather than by the operating system. In this case, for recall of page data stored in the memory 17, the system of Figure 1 would send a page address (plus controls), and if the disk controller found this address in a table maintained of pages on disk then a disk read would be implemented and the page returned to the CPU for writing to main memory.

11. The controller for the memory 17 would also search for the page address in a table maintained locally to determine if the page was stored in the partitions 18 or 19 as compressed data, and if so the page would be read from the indicated location in partition 18 or 19 and uncompressed before returning
5 the page to the CPU via bus 12 in an uncompressed state. Of course, the page would be found in either the disk 14 or the memory 17, but not both. The CPU 10 would merely send out an address on the bus 12 (e.g., the virtual memory address) to recall a given page, and would not itself need to keep track of whether the page was stored compressed, nor which partition was used
10 to store a given page.

With reference to Figure 2, one example of the construction of the data compression mechanism 16 and its memory controller of Figure 1 using the features of the invention is illustrated. The compression mechanism receives
15 data from the CPU 10 by the bus 12 which typically would include an address bus 12a, a data bus 12b and a control bus 12c, all being input to a bus interface unit 22. The interface unit 22 provides a DMA interface so that four-word bursts of data may be transferred from the system bus into or out of the mechanism 16, thereby increasing the overall DMA transfer rate. A FIFO
20 23 buffers incoming and outgoing data to or from the bus 12. The FIFO 23 is four words deep, i.e., has a data width of 32-bits (one word) and is four bits deep for every bit position. A burst-sensing arrangement in the interface controller 24 generates a Bus-Request for control bus 12c whenever at least one word is in the four-word FIFO 23 ready to transfer to the bus 12; when
25 the CPU responds with a Bus-Grant on control bus 12c, the FIFO is checked to see how many words are ready for transfer, and produces a burst of that many words (up to four) onto the bus 12. If only one word is ready, then of course only one word will be transferred. Similarly, up to four words can be accepted in a transfer from the CPU 10 to the unit 11 via the bus 12;
30 depending upon how many words are in the FIFO (not yet processed) and how many words the CPU has ready to send, up to four words can be transferred in

a burst, under control of the controller 24. After transfer into the FIFO 23, the data is fed one byte at a time to a compression mechanism 26 via bus 27, using an 8-bit output buffer 28. The buffer 28 is loaded from the FIFO by a 1-of-4 selector 29 which selects one of the four bytes of a word, and by a 1-of-4 selector 30 which selects one of four words in each four-deep bit position 31. A counter 32 operated by a clock 33 (e.g., the system clock for the CPU 10) controls the selectors 29 and 30. This same clock controlling the compression mechanism 26 and other parts of the mechanism 16, as well. The controller 24 may respond to commands on the bus 12 in a manner similar to a disk controller, i.e., the CPU 10 sends commands and data by writing to registers in the bus interface controller 24 using the buses 12a, 12b and 12c in the I/O space of the CPU. The CPU 10 may send a page to be stored in a format including commands on control bus 12c, an address field on address bus 12a, and a 4Kbyte data field in bursts of four 4-byte words. An important feature of the construction of the FIFO 23 is that it uses shift register cells instead of flip-flop (static) cells or a RAM array, which allows the FIFO to be implemented in a much smaller number of gates in a gate array.

Data to be stored, received from the CPU 10 via FIFO 23, is directed by the 8-bit bus 27 to the data compression mechanism 26, one byte each clock cycle. The data compression mechanism 26 may be of various types of construction, and serves to accept fixed-length segments of data from bus 27, one byte at a time, and to ultimately produce variable-length pages of output data on output bus 34. The compression method used is preferably a unique implementation of the so-called Lempel-Ziv type as described by Ziv, J. and Lempel, A., "Compression of individual sequences via variable-rate coding", IEEE Trans. on Information Theory, Sept. 1978, pp. 530-536, or other improvements may be used such as described by Terry A. Welsh, "A technique for high-performance data compression", IEEE Computer, June 1984. The mechanism 26 may be a processor itself, executing code, or may be a sequential state machine, or preferably a logic network constructed of gate

arrays. The amount of compression of a given page of data will depend upon the degree of repetitiveness of patterns of characters in the page, since the compression technique is based upon the concept of substituting a shorter code symbol in place of a sequence of bytes which has appeared before in the page.

5 In the improved implementation, a window is examined in a 64X8-bit register 35 using a 4X8-bit lookahead buffer 36, and the one-clock compare logic 37 produces a match output 38, a match address output 39 and a match length output 40, in one clock cycle. This compression mechanism operates upon one to four byte segments of data and performs a single-clock compression of this
10 data if a match is found. The Lempel-Ziv compression circuitry employed performs comparisons of all match sizes of the lookahead buffer 36 of all positions in the window 35, for single-clock compression of all matches (one to four bytes). A tuned Lempel-Ziv algorithm uses 8-bit symbols, with a 64-symbol window 35, and a four-symbol lookahead buffer 36. This algorithm
15 produces output values on the bus 34, each clock cycle, that are the same bit-width (9-bits) for either match or no-match to greatly simplify the task of bit-packing the compressed output. This compression mechanism is pipelined so that one byte is passed every clock cycle.

20 The 9-bit data on bus 34 is applied to an ECC generate circuit 45, to produce a code that is stored with each block, then upon recall an ECC detect/correct circuit 46 checks the code and makes a correction if a recoverable error is detected. The ECC logic uses a BCH code with a 9-bit character size to effectively correct errors on the 9-bit compressed data, one 9-
25 bit byte at a time, as it comes in on the bus 34. A linear feedback shift register, with the 9-bit symbols in bit-parallel, receives the incoming data and generates the ECC code on the fly in the generator 45.

The DRAM controller 49 receives the 9-bit data from bus 47 into a 9-
30 bit buffer 50, and loads this data into a word-wide two-word buffer 51 via a selector 52. The buffer 51 is 4X9-bits wide (one word) and two words deep, so

there can be two 36-bit words ready to apply to the 36-bit wide memory bus 53 at any given time. The memory 17 is configured as two banks 55 and 56 of DRAM devices, preferably 4-Meg, 16-Meg or larger for each memory device. Note that the DRAM storage for compressed data is arranged in a bit-width
5 (36-bits) that is a multiple of the compressed data size (9-bits) to simplify the task of circuitry which bit-packs the compressed output. If the depth of the partition 18 were 512-words, a DRAM having 2048 columns would fit four pages in one column width. Then, if the partition 19 was about 70% of a 1024-word page size, three pages would fit in a column. The object is to fill
10 the DRAM with a minimum of unused memory area, for maximum economy. The two-word buffer 51 along with sensing logic in control circuitry 54 responsive to the content of the buffer provides a page-mode write, thereby decreasing the effective memory cycle time; when one word of data is ready to be written to the DRAMs, a write cycle is initiated (involving RAS going
15 active and write-enable going active), and if a second word of data is in the buffer 51 ready to be written before the write operation is completed (before CAS goes inactive-high) and if the second word is to be written to the same page, then the normal single-word write is changed to a page-mode write (CAS goes inactive-high while RAS stays active-low, then CAS goes active-low again)
20 and both words written in one RAS cycle. The controller 13 generates a single set of RAS and CAS strobes on lines 57 and 58 for each two banks 55 and 56 of DRAMs, along with separate sets of write-enable and output-enable controls on lines 59 going to the two banks. This economizes on the number of output pins needed for the gate array used to construct the DRAM
25 controller.

The operations in the system of Figure 2 are pipelined, so in a single clock cycle a number of operations are taking place. In a compression operation, a data byte is transferred from the FIFO 23 into the lookahead
30 buffer 36 via buffer 28 and bus 27 in a clock cycle, so a new byte is added to the lookahead buffer in each clock. A comparison is made of a byte in the

lookahead buffer 36 with the 64-byte sliding window 35 and a match indication or symbol vector, or non-match character, is generated in each clock cycle. A symbol vector or non-match character is presented to the ECC circuit via bus 34 in a clock cycle (some cycles are skipped when a match is pending), and a 9-bit ECC symbol is presented to the buffer 50 via bus 47 in a clock cycle. A 36-bit word is available in the buffer 51 every four clock cycles for storage in the slow DRAM memory 17. In a decompression operation, a 36-bit word (multiple ECC-based symbol vectors and/or characters) is transferred from the slow DRAM 17 to the buffer 51 so that a 9-bit symbol is available to the ECC circuit via buffer 50 and bus 47 in each clock cycle. The ECC detection is carried out in the detection/correction circuit 46 at the rate of one symbol per clock. In the decompress circuit 60, which uses the same lookahead buffer 36 and sliding window 35, a 9-bit symbol is converted or a non-match character is transferred to the sliding window in a clock cycle. And, data is transferred from the sliding window 35 to the FIFO at one byte per clock, to on average the transfer rate to the system bus (at four bytes per word) is one byte per clock or one word per four clocks.

Referring to Figure 3, the compression circuitry in the mechanism 16 includes a four-byte lookahead buffer 36 and a sixty-four byte window buffer 35, with the data from the buffer 28 being clocked into the right-hand end, one byte each clock cycle. The compare circuitry 37 checks to see if any two-byte, three-byte or four-byte sequence in the window 35 is the same as what is in the lookahead buffer 36, and, if so, substitutes the address (in the range 0-63) of the beginning of the sequence and the length (2-, 3- or 4-bytes) of the sequence, in place of the data itself, as the address 39 and the length 40. Thus, a 9-bit output data value is sent to the ECC circuit from the compare circuit that is either (1) a value of the format 61 seen in Figure 3 which has a field 62 which is the same as the input data byte with a 9th bit in field 63 that indicates no-match, or (2) a value of the format 64 which includes a 6-bit address field 39 and a 2-bit length field 40 indicating how many bytes are

matched, along with a 9th bit in field 63 that indicates "match data". In a clock cycle, the byte in position A of the lookahead buffer 36 is compared with all 64-bytes of data in the window 35 (bytes 0-63) by a set of sixty-four compare circuits 67, one for each position of the window 35. If no compare is found in
5 any of the sixty-four compare operations performed, the original character is sent out as the 9-bit format 61, the data shifts one position to the left in window 35 and buffer 36, a new byte enters at position D of the lookahead buffer 36, and another 64-position compare is made of the byte now in position A. If a compare is found, a hold is set in a flip-flop 68 for this position (0-63)
10 of the window 35, and a left shift is executed and a new byte of data enters the right-hand position D of the lookahead buffer. Another byte is now in the position A (the byte that was previously in position B) and another compare is made by the sixty-four compare circuits 67. If another compare is found, this means that there are two adjacent bytes that are identical to two adjacent
15 bytes in the window. The "hold" condition previously set in the flip-flop 68 is held, using the AND gate 69, as will be explained, and another left shift is executed in the next clock, with another new byte entering position D. Another compare is performed by the sixty-four circuits 67, and this continues up to four compares. That is, the maximum number of identical bytes to be
20 found is four, and these four are replaced with one 9-bit value of format 64 in the data stream sent to the ECC circuit via bus 34. So, if a 4Kbyte page of 8-bit data was sent to the compression circuit 26 composed of all identical values (e.g., all zeros) the maximum compression produces 1024 9-bit characters or symbols of format 64, or to 28% of the original. During clocks where a match
25 has been found, the output on bus 34 is a null or no-op, so there are gaps of one, two or three clock cycles when no output value is placed on the bus 34 from the compression circuit.

Each one of compare circuits 67 has two 8-bit inputs 70 and 71, with the
30 input 70 being the contents of one of the window 35 positions (bytes 0-63), and the other input 71 being the contents of the position A of the lookahead buffer

36. If the contents are identical, an equality indication is produced at an output 72. This output is applied to the NAND gate 69, and the output 73 of the gate is applied to the flip-flop 67. The flip-flop is initialized to a "match" state after each data value is outputted to bus 34, so the feedback via line 74
5 from output 75 allows the AND gate 69 to pass the match output 72 if it is high, indicating a match for the present compare. So, on the first clock, the byte compare is ANDed with the flip-flop output 75 to indicate if there is another match, and, if so, that state is latched (maintained) in the flip-flop by the input 73. All of the sixty-four flip-flops 68 at positions where there is no
10 match will be switched to the "off" condition, so they will no longer be in contention for a multiple-byte match. After four clocks, only the flip-flops 68 of the sixty-four that have registered four matches in a row will still be "on". The sixty-four flip-flop outputs 75 go to a priority encoder 76 to generate on lines 77 the 6-bit address 39 of the lowest-number first byte of a four-byte
15 match, i.e., the match closest to the lookahead buffer 36. After the match address is sent out as a format 64 match symbol, all flip-flops 68 are initialized to the starting state for a new compare cycle. If, after only three bytes have matched, the fourth byte shows no more matches, the current outputs of the flip-flops are immediately sent to the priority encoder 76 to generate the
20 address of the 3-byte match. Similarly for 2-byte matches. A line 78 connects the output 73 of each of the sixty-four NAND gate 69 to a 64-input OR gate 79 to produce an output 80 to indicate there is a match somewhere in the window 65; so long as the output 80 is high, a new compare cycle is not started. The number of cycles that the output 80 stays high is used to generate
25 the length field 40 of 2-, 3- or 4-bytes.

Instead of the compare circuit shown, where only one of the bytes of the lookahead buffer 35 is compared to the window 35 each cycle, the entire four bytes of the lookahead buffer can be compared in a single "gang compare"
30 cycle. In such a case, if a four-byte compare was detected, the symbol 64 would be sent out as described above, then there would be three no-op cycles

where no compare is done while new data is shifted into the lookahead buffer. The one-byte at a time compare as described above requires up to 75% fewer gates in a gate array for implementation, however, and still maintains the throughput speed of one clock per byte input. Also, the number of bytes in the lookahead buffer 36 could be increased, but this would require a larger format 61, 64 for the output symbols. If the number was eight, the field 40 would be 3-bits, for example. Likewise, an increase in the number of bytes in the window 35 is possible, and again would require an increase in the number of bits in the address field 39.

10

An example of a compression sequence using the circuit of Figure 3 is illustrated in Figure 4. The input string in the example is the text "THIS_IS_TEST_A__THIS_IS_TEST_B__..." No match is found until after the fifth clock cycle, then a 3-byte match is found for "IS_" at address "02" which is clocked out on the sixth cycle. Then no match is found until clock seventeen where "_T" is matched at address "07" and clocked out at the seventeenth cycle. Four-byte matches are found to be clocked out at cycle-18, -22, -26 and -31. In this example the number of input bytes is thirty-six, and the number of output symbols is twenty, providing a compression to 62.5% of original size.

20

The decompression operation uses the same 64-byte window buffer 35 as is used for compression. The 9-bit symbols from the bus 34 are loaded, one each clock cycle, to the buffer 82, and the ninth bit field 83 is used to determine whether the symbol is compressed or not. If not compressed the 8-bit field 62 which is the original character is loaded to byte-0 of the window 35 via lines 84. If compressed (field 83 a "1") the address field 39 is applied by path 85 to a 1-of-64 selector 86, while the number field 40 is applied via path 87 to a selector 88 which picks 2-, 3- or 4-bytes starting at the location selected by the selector 86, and feeds this value back to the byte-0 position via path 89 and lines 84, as the contents of window 35 are clocked to the left according to

25

30

the number in field 66. Decompression thus proceeds at the clock rate, one byte per clock. The decompressed data is applied to the bus 27 at the same time it is shifted into the byte-0 position, and consists of the reconstructed original data.

5

Referring to Figure 5, the ECC encoder circuitry 45 is illustrated. The input from the bus 34 is a series of 9-bit data words as generated by the compression circuit. The output to the bus 47 from the ECC encoder 45 is a sequence of fifty-six 9-bit data words as illustrated in Figure 6. An input of 10 485 data bits (in 53 9-bit symbols plus 8-bits) has nineteen parity bits added to it to produce the output sequence of 56 9-bit words, a total of 504 bits, labelled x^0 to x^{503} in Figure 6. This is referred to as a (504, 485) code.

The generator polynomial used in the encoder of Figure 5 is

15

$$g(x) = m_0(x) \cdot m_1(x) \cdot m_3(x)$$

where

$$m_0(x) = x + 1$$

$$m_1(x) = x^9 + x^4 + 1$$

$$m_3(x) = x^9 + x^6 + x^4 + x^3 + 1$$

20

The polynomials are from Table C.2 of Peterson & Weldon, "Error-Correcting Codes", MIT Press (1972). Multiplying these polynomials gives

$$g(x) = x^{19} + x^{18} + x^{16} + x^{15} + x^{13} + x^{12} + x^{11} + x^{10} + x^9 + x^6 + x^4 + x^3 + x + 1$$

25

Encoding is performed by dividing the shifted message polynomial $x^{19}m(x)$ by $g(x)$ and appending the remainder $p(x)$ to $x^{19}m(x)$ to form a code word. That is, if

$$\frac{x^{19}m(x)}{g(x)} = q(x) + \frac{p(x)}{g(x)}$$

Then

$$c(x) = x^{19}m(x) + p(x)$$

Operation of the encoder circuit of Figure 5, which functions in bit-parallel, is best explained by first referring to Figure 7, where a conventional bit-serial feedback shift circuit is shown which would encode this (504, 485) code. This is an encoder for $g(x)$, using premultiplication by x^{19} . The serial input data $m(x)$ enters at input 75 and exits at output 76, and is also applied to the feedback loop 77 via gate 78, where the last 19-bits of a 504-bit series are masked by an input 79. The sequence of gates 80 and delays 81 results in an output of nineteen parity bits on line 82, following the 485-bit serial data on line 76. Figure 8 shows a circuit which performs exactly the same function as the circuit of Figure 7, but uses premultiplication by x^{18} . In operation the 485-bit message polynomial is shifted into this register at input 84 and path 85, and simultaneously shifted out to the channel at output 86, then the register is shifted once with a zero input. During this time the encoder outputs the high-order parity bit (in position x^{18}) at output 87. At this point the feedback connection via gate 88 is disabled and the last 18-bits of the parity check polynomial are shifted out via output 87.

20

Figure 5 shows a circuit which performs the same function as the encoder of Figure 8; it differs in that it inputs nine data bits at a time, in bit parallel, accepting the symbols of format 61 or 64 from the compression mechanism 26. In operation, the encoder circuit of Figure 5 receives on nine parallel lines 84 as input the 485 data bits with a single trailing zero, as fifty-four 9-tuples or 9-bit symbols. This data is also output on nine lines 86 (only one shown). After the last 9-bit symbol (which contains the trailing zero) is input the encoder contains the nineteen parity checks (to be bits $x^0 - x^{19}$ of Figure 5). The high-order parity check bit x^{19} is then output on line 89 and substituted for the trailing zero in the last data symbol, and the remaining eighteen parity checks are outputted as two 9-tuples on lines 87. The resulting

30

code word, which consists of fifty-six 9-bit symbols, is depicted in Figure 6. The two 9-bit registers holding p_0 to p_8 , and p_9 to p_{17} , are each made up of nine flip-flop circuits.

5 The truth table of the circuit M_e in Figure 5 is given in Table 1. This table indicates which of the nine inputs $M_1 + f_{10}$, $m_2 + f_{11}$, ..., $m_8 + f_{17}$, f_{18} must be XORed to produce each of the nineteen outputs $f_0 f_1 \dots f_{18}$. For example, the right-most column of the table shows that

$$f_{18} = (m_1 + p_{10}) + (m_8 + p_{17})$$

10 while the left-most column shows that

$$f_0 = (m_1 + p_{10}) + (m_2 + p_{11}) + (m_3 + p_{12}) + p_{18}$$

Because the code has nineteen parity check bits, the high-order parity check bit (f_{18} in Figure 5) must be inserted into the low-order position (m_0) of the last data symbol. Thus the encoder of Figure 5 must be augmented by a
15 2:1, 1-wide, mux (accepting the outputs 87 and 89) to implement this substitution.

The ECC decoder 46 is illustrated in Figure 9. This circuit receives the fifty-six 9-bit words from the DRAM via bus 47 and produces a 9-bit wide
20 output to bus 34, with fifty-six 9-bit input words producing an output of $53+8/9$ 9-bit words. The fifty-six symbols go into a buffer 90, and if no error is detected, the data is shifted out beginning right after the 56th symbol shifts into the buffer 90. The nineteen parity bits are stripped off before the data is shifted out. There will be no errors in the vast majority of ECC blocks shifted
25 in; errors will occur only once in hours of operation.

The first step in decoding the received word $r(x)$ in the circuit of Figure 9 is to compute three partial syndromes in the syndrome circuits 91, 92 and 93. These are

$$\begin{aligned} 30 \quad S_0 = r(1) = e(1) &= 0 \text{ if } 0, 2, 4, \dots \text{ errors} \\ &= 1 \text{ if } 1, 3, 5, \dots \text{ errors} \end{aligned}$$

-24-

$$S_1 = r(\alpha) = e(\alpha) = \sum_{i=1}^v x_i$$

$$S_3 = r(\alpha^3) = e(\alpha^3) = \sum_{i=1}^v x_i^3$$

Here the x_i are the error locations and v denotes the number of errors. If $v = 0$ then $S_0 = S_1 = S_3 = 0$. Note that S_0 is a 1-bit quantity while S_1 and S_3 are 9-bit elements of $GF(2^9)$.

In the event there is only one error, then

$$S_0 = 1 \quad \text{and} \quad S_1^3 + S_3 = 0$$

In this case the location of the single error is given by $x_1 = S_1$.

If two errors occur these partial syndromes are related to the coefficients of the error locator polynomial

$$\Sigma(x) = (x + x_1)(x + x_2) = x^2 + \sigma_1 x + \sigma_2$$

by the key equations

$$S_0 = 0$$

$$S_1 = \sigma_1$$

$$S_3 = S_1^2 \sigma_1 + S_1 \sigma_2$$

These equations can be solved to give

$$\sigma_1 = S_1$$

$$\sigma_2 = \frac{S_3 + S_1^3}{S_1}$$

Factoring $\Sigma(x)$ gives its two roots x_1 and x_2 . With x_1 and x_2 known, decoding is complete.

When three errors occur

$$S_0 = 1 \quad S_1^3 + S_3 \neq 0$$

This combination of events can always be used to detect a three-error pattern. Some odd-weight patterns with five or more errors will also be detected in this way.

The ECC partial syndrome calculators 91, 92 and 93 are circuits for computing the three partial syndromes S_0 , S_1 , and S_3 . Figure 10 shows the S_0 -calculator 91, which is a circuit that simply computes the sum (modulo 2) of all of the 504 bits of the received word. Figure 11 shows a bit-serial circuit 92 which computes

$$S_1 = r(\alpha) = r_0 + r_1\alpha + r_2\alpha^2 + \dots + r_{503}\alpha^{503}$$

Figure 12 shows a symbol-wide circuit 92 which performs the same function on nine bits $r_0 - r_8$ as Figure 11 does on one bit. The operation of this circuit will be explained and the function performed by the circuit M_1 defined.

Denoting the present state of the bit-serial circuit by $P = (p_8 p_7 p_6 \dots p_0) = \alpha^P$, and inputting the polynomial $r(x) = r_8x^8 + \dots + r_0$, after nine shifts the register will contain

$$\begin{aligned} \alpha^f &= ((\alpha^P\alpha + r_8)\alpha + r_7)\alpha + r_6)\alpha + \dots + r_0 \\ &= \alpha^{P+9} + r(\alpha) \end{aligned}$$

Thus if the circuit M_1 in Figure 12 is designed so that it multiplies its input (p_0 to p_8) by α^9 , this circuit 92 will perform the same calculation as that of Figure 10.

If the contents of the 9-bit register 95 are presented as

$$p(x) = p_8x^8 + p_7x^7 + \dots + p_0$$

then to multiply by α^9 we must simply calculate

$$\alpha^9 p(x) = p_8\alpha^{17} + p_7\alpha^{16} + \dots + p_0\alpha^9$$

The truth table of an α^9 -multiplier is shown in Table 2. After the 56th clock (56-symbol input) the register 95 contains the 9-bit S_1 syndrome, which is output to the error corrector 96.

5 Figure 13 shows a bit-serial circuit 93 which computes

$$S_3 = r(\alpha^3) = r_0 + r_1\alpha^3 + r_2\alpha^6 + \dots + r_{503}\alpha^{1509}$$

If the present state of this circuit is denoted by $\alpha^p = (p_8, p_7, \dots, p_0)$ then after nine shifts the register 97 will contain

$$\begin{aligned} \alpha^f &= ((\alpha p_8 + r_8)\alpha^3 + r_7)\alpha^3 + \dots + r_0 \\ 10 \quad &= \alpha^{p+27} + r(\alpha^3) \end{aligned}$$

Figure 14 shows a symbol-wide syndrome generator circuit 93 which performs the same function as the serial circuit of Figure 13. Table 3a shows the truth table of the circuit M_3 (which multiplies by α^{27}), while Table 3b shows the corresponding table for the circuit M_0 (which evaluates $r(x)$ at α^3). The
15 register 97 made up of nine flip-flops contains the S_3 syndrome after the 56th clock.

Referring to Figure 15, the error corrector 96 in the decoder of Figure 9 is shown in more detail. The circuit performs the functions necessary for
20 decoding as explained above. In operation, as the received word enters the decoder, the three partial syndromes are calculated in the circuits 91, 92 and 93. After the last 9-bit symbol enters, these three syndromes are checked for all zeroes (by a controller, not shown). If they are all zero, the data block is assumed to be correct and is outputted from the data buffer 94 to the bus 27.
25 If any of the partial syndromes are non-zero, then the error-correction process explained below is executed. In this case, data flow is halted until correction is complete. The likelihood of an error is very small, probably not occurring more than once every few hours in typical operation, so the performance penalty due to data correction is virtually zero.

30

The first step in the error correction process is the computation of S_3/S_1^3 . Note that

$$S_1^{-3} = S_1^{508} = ((S_1^{127})^2)^2$$

and that

$$S_1^{127} = S_1^1 \cdot S_1^2 \cdot S_1^4 \cdot S_1^8 \cdot S_1^{16} \cdot S_1^{32} \cdot S_1^{64}$$

Thus S_1^{-3} can be calculated by an appropriate sequence of squarings and multiplications. Table 4 shows the sequence of steps involved in this calculation, using the F and G registers of Figure 15, along with a squaring circuit 98 and a multiply circuit 99, and 3:1 selectors 100 and 101. After this sequence of steps is performed, S_3 is multiplied by S_1^{508} in the multiplier 99 and the result stored in Register G. This circuit 102 for performing the function of generating $S_3 S_1^{-3}$ would ordinarily be done in a look-up, using a ROM for storing the values; to reduce the area required in constructing the circuitry, the functions of Figure 15 are implemented.

15

Adding 1 (i.e., inverting the lower-order bit) of this result gives the quantity

$$A = 1 + \frac{S_3}{S_1^3}$$

20

used in factorization of the quadratic $L(Z)$.

Here the 8-tuple A^* on line 103 is formed by deleting the lower-order bit of A and then multiplying A^* by the matrix $(M_8^*)^{-1}$ in a circuit 104. The resulting 8-bit product, with a 0 appended in the lower-order position, is the quantity Z_1 on line 105. Then Z_1 is multiplied by $\sigma_1 (= S_1)$ in multiplier 106 to give the first error-location number X_1 on line 107; next the second error-location number is calculated in exclusive-OR circuit 108:

$$X_2 = X_1 + S_1$$

30

At this point both error locations are fed to the mapper 109, as inputs X_1 on lines 107 and X_2 on lines 110 (both 9-bits wide); the mapper 109 is shown in

detail in Figure 16. Basically this mapper circuit generates all possible error-location numbers from α^{503} to α^0 in descending order; this circuit function could also be accomplished by a look-up using a ROM containing these values, but is preferably implemented as the circuit of Figure 16 for construction in a gate array. The mapper circuit of Figure 16 computes these location numbers in sets of nine; first it computes $\alpha^{503}, \alpha^{502}, \dots, \alpha^{495}$ using the register 111 initialized to α^{495} and the feedback of α^{-9} via path 112; then it computes $\alpha^{494}, \alpha^{493}, \dots, \alpha^{486}$, etc. At each step it compares X_1 and X_2 to these numbers using the compare circuits 113 receiving the computed numbers on lines 114, and, if it finds a match, it outputs a 1 on lines 115 in the appropriate bit of the correction symbol. Figure 17 shows a circuit which can be used for these comparison circuits 113, employing an exclusive-OR circuit 116 and a NOR gate 117.

The process of computing the error location numbers $\alpha^{503}, \alpha^{502}$, etc., involves multiplication by various powers of α , as shown as multiplier circuits 118 in Figure 16. Table 5 shows the matrices for the nine fixed-element multipliers 118 used in Figure 16.

This completes the correction process. It is necessary also to consider the task of detecting error patterns which are not correctable, i.e., error detection. In addition to correcting one or two bit errors per block, the code can detect all triple-error patterns and about three-quarters of higher weight patterns. Errors are detected in two ways:

Condition 1) Inconsistency between partial syndrome S_0 and number of errors corrected.

Condition 2) $A = 1 + (S_3/S_1^3)$ does not satisfy the constraint $a_0 = a_5$.

To check Condition 1 it is necessary to count the number of corrections made by the error corrector. The implementation of the error counter 120 of Figure 15 is straightforward, merely counting the output 115 of the mapper

109. The error detection logic 121, seen in Figure 18, is responsive to the S_0 output from the generator 91, the output 122 from the error counter 120, and one bit of the A output from the circuit 102. Basically the partial S_0 syndrome must be 0 if an even number of errors is corrected and 1 if an odd number.

5 Table 6 lists the six possible combinations of S_0 and the Error Count which can occur. The table shows that Condition 1 is easily detected with a single XOR-gate 123.

Checking Condition 2 is straightforward; if $a_0 = a_5$, an uncorrectable error has been detected. Figure 18 shows a logic circuit which can be used to generate the detection flag on output 124 in the error corrector 121 of Figure 15, using the two exclusive-OR circuits 123 and 125, and an OR gate 126. The detection flag is used by the system, i.e., the CPU 10, as status to evaluate what action to take; usually a fault would be generated using an interrupt

15 when an uncorrectable error is detected.

Another feature of one embodiment of the invention is the dynamic allocation of partitioning of the memory 17. The relative sizes of the partitions 18 and 19 in the memory 17 are chosen to fit the data being compressed. This may be done on an empirical basis, using the history of compressing page data for a particular task or application. According to another embodiment of the invention, the partition sizes can be calculated on a dynamic basis using the currently executing pages.

20

25 The logical size of a block of data handled by the system described above is a page, which is typically 4096 8-bit bytes. Usually the system addresses data in memory 11 by 8-bit bytes or 32-bit words. The compression system of Figure 2, however, handles data in components to the right of the compression mechanism 26 in 9-bit bytes or 36-bit words. The memory 17 is

30 purely a block addressable device, and, with data compression and ECC,

handles 4096-byte pages (after compression and ECC bits added). The ECC logic maintains 56-bit words.

The maximum compression capability of the system of Figure 2 is to
5 replace four 8-bit data bytes on bus 27 with one 9-bit data symbol on bus 34.
The ECC circuit generates onto bus 53 a 56-symbol block (Figure 4) for each
53+ (9-bit)-symbols on bus 34. This ECC output is rounded to the next higher
56-symbols (a symbol is a 9-bit "byte"). Thus, for a system page size of 4096 8-
bit data bytes, the effective page size in 9-bit ECC symbols is
10 $(4096/4)*(56/53)$, rounded up to next 56 = 1120 (9-bit ECC symbols)
This is equivalent to twenty (i.e., 1120/56) ECC blocks. Since bits are added
to the data being compressed and ECC parity bits are added, a page that is
totally uncompressable would have one bit added to each byte in the
compression mechanism 26 and expanded by a factor of 56/53 in the ECC
15 generator 45 (plus round up), so 4869+ bytes theoretically would be produced
for storing in the memory 17. The driver used to manage the system of Figure
2 assures that only pages that compress to below certain thresholds will be
stored in partitions 18 and 19, however. Those pages that expand are simply
marked in error and not stored. Since system pages compress to various sizes,
20 a method is provided to manage the data as variable length records.

Compression runs on typical data found in swap operations in a virtual
memory system provide the basis from which certain empirical values can be
chosen. The driver used with the system of Figure 2 manages the swap
25 memory 17 as a "house". The house contains rooms 20-through-65, divided
into floors to best accomplish the task of managing variable length pages.
Pages which expand to greater than sixty-five ECC blocks are said to be
evicted. For each device of Figure 2, a separate data file is maintained which
is mapped into kernel space during execution so that continuously updated
30 data points may be more efficiently accrued. If the device's data file (known
as a tenants file) did not at first exist, then one is created during the device

open and filled with the data points obtained from software simulation runs.
(known as applicants).

5 The tenants correspond to the number of pages which compress to fit in
a particular room. The percentage of potential fits in a room to the total
number of rooms is then derived for each tenant, as well as their effective
compression ratios. The values BASEMENT and ATTIC are established to
represent the limits on rooms within the house; popularity establishes the
percentage of hits on those rooms; and efficiency establishes the effective
10 compression percentage for each room.

```

15           #define     BASEMENT       20
             #define     ATTIC         65
             #define     ROOF         ATTIC + 1

             double     tenants[ROOF-BASEMENT];
             double     popularity[ROOF-BASEMENT];
             double     efficiency[ROOF-BASEMENT];

20           leases = 0;
             for (room = BASEMENT; room < ROOF; room++)
                 leases += tenants[room-BASEMENT];
             for (room = BASEMENT; room < ROOF; room++)
25           {
                 popularity[room-BASEMENT] =
                          tenants[room-BASEMENT] / leases;
                 efficiency[room-BASEMENT] =
                          room * (9/8) * (56) / 4096;
             }
30           }

```

The tenants array always exists and is continuously updated; however,
the popularity and efficiency arrays are calculated once on the initial open of
the device and are merely place holders until the house is constructed. The
floorplan of the house consists of the following:

```

35           struct     floorplan
             {
                 long     screen;
                 long     window;

```

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```

5      long      door;
      long      front;
      long      back;
      long      area;
      double    efficiency;
      double    popularity;
      }model[ROOF-BASEMENT],house[ROOF-BASEMENT];

```

10 The house was decided to have four floors. Obviously, the more floors, the more effective the storage; however, the program used to size the floors would take longer to run and a desire is to maintain a large first floor for a better first hit percentage. Therefore, a small change in compression is allowed to facilitate a larger change in space.

```

15      floors      = 4;           /* number of floors */
      stax         = 0.020;       /* size tax (compression delta) */
      wtax         = 0.080;       /* weight tax (population delta) */

```

20 The house is constructed using the values above to find the floors which provide the most compression (plus or minus stax) given the largest floor space (plus or minus wtax). All combinations of floor space are analyzed, from...

```

25      20 - 20
      21 - 21
      22 - 22
      23 - 65

```

to...

```

30      20 - 61
      62 - 62
      63 - 63
      64 - 65

```

35 First, the popularity of all the rooms on a floor are summed and stored in the house. A door is opened between the two rooms joining each floor, while the effective capacity of each floor is computed and summed with that of the previous floor. Suppose the following floors are being analyzed:

```

      20 - 24
      25 - 36

```

37 - 46

47 - 65

5 The popularity of rooms 20 through 24 are summed and stored in the
 house beside the room which divides the floors (room 24). The same is
 performed for the other three floors, saving the most popular floor. The
 combined effective compression is computed by summing the products of each
 floor's efficiency and popularity. The overall effective capacity is thus the
 10 physical capacity of the device divided by the total effective compression. The
 weight of the house is computed as the popularity of the largest floor divided
 by the total effective compression. Since the goal is to achieve a house with
 the smallest possible total effective compression and the largest floor, a small
 increase is allowed in compression for every large increase in population on
 the most popular floor. An example of a constructed house's floorplan might
 15 be as in Figure 19.

The code sequence which accomplishes all this is as follows:

```

    scap = 1.;
    scap = 0.;
    20    blueprint(BASEMENT,floors,ATTIC,stax,wtax);
  
```

```

    blueprint(room, floors, attic, stax, wtax)
    25       long            room;
          long            floors;
          long            attic;
          double          stax;
          double          wtax;
    30       {
          long            a,b;
          double          pop;
          double          iscap;
          double          iwcaps;
    35       if (floors < 2 || floors > attic - room)
              return;
          for (a = room+1; a < attic; a++)
  
```

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```

{
    pop = 0.;
    for (b = a; b > room | | b == BASEMENT;)
        pop += popularity[b-BASEMENT];
5    model[a-BASEMENT].popularity = pop;
    model[room-BASEMENT].door = a;
    if (floors > 2)
    {
        blueprint(a,floors-1,attic,stax,wtax);
10        continue;
    }
    pop = 0.;
    for (b = attic; b > a; b--)
        pop += popularity[b-BASEMENT];
15    model[attic-BASEMENT].popularity = pop;
    model[a-BASEMENT].door = attic;
    model[attic-BASEMENT].door = BASEMENT;
    b = BASEMENT;
    iscap = 0.;
    pop = 0.;
20    while ((b = model[b-BASEMENT].door) !=
BASEMENT)
    {
        iscap += (efficiency[b-BASEMENT] *
25        model[b-BASEMENT].popularity);
        if (pop < model[b-BASEMENT].popularity)
            pop = model[b-BASEMENT].popularity;
    }
    iwcap = pop/iscap;
30    if ((iwcap > wcap) && (iscap < scap)) | |
        ((iwcap > wcap - wtax) && (iscap < scap - stax)))
    {
        scap = iscap;
        wcap = wcap;
35        do
            house[b-BASEMENT] = model[b-
BASEMENT];
        while((b=model[b-BASEMENT].door)!=BASEMENT);
    }
40 }
}

```

The floors are next furnished and sorted by popularity--the most popular floor being addressed first.

floorsort(BASEMENT);

```

5  -----
    floorsort(basement)
      long          basement;
10  {
      double        lpopularity, rpopularity;
      long          lroom, mroom, rroom;

      while ((lroom = house[basement-BASEMENT].door) !=
15          BASEMENT)
      {
          lpopularity = house[lroom-BASEMENT].popularity;
          mroom = lroom;
          rroom = house[mroom-BASEMENT].door;
          if (rroom == BASEMENT)
20              break;
          rpopularity = house[rroom-BASEMENT].popularity;
          while (lpopularity >= rpopularity)
          {
              mroom = rroom;
25              rroom = house[mroom-BASEMENT].door;
              if (rroom == BASEMENT);
                  break;
              rpopularity =
                  house[rroom-BASEMENT].popularity;
30          }
          house[basement-BASEMENT].door = rroom;
          house[mroom-BASEMENT].door =
              house[rroom-BASEMENT].door;
          house[rroom-BASEMENT].door = lroom;
35      }
          if (rroom == BASEMENT)
              basement = lroom;
      }
40  }

```

From Figure 20 it can be seen that the first floor occupies rooms 25 through 36, the second floor occupies rooms 20 through 24, and so on. For

instance, all pages which can compress to less than or equal to 36 ECC blocks and greater than 24 blocks are addressed in the range 0 through 32325632. The area maintained by a floor is computed as the total effective capacity of the device divided by the effective capacity of that floor.

```

5      ecap = pcap / scap;
      lcap = 0;
      room = BASEMENT;
      while ((room = house[(door=room)-BASEMENT].door) !=
10     BASEMENT)
      {
          house[room-BASEMENT].capacity =
              (efficiency[room-BASEMENT] *
                house[room-BASEMENT].popularity);
          house[room-BASEMENT].efficiency =
15         efficiency[room-BASEMENT];
          house[room-BASEMENT].area = (long)roundoff((ecap *
              house[room-BASEMENT].popularity),
              (double)(0-4096);
          lcap += (double)house[room-BASEMENT].area;
20     house[room-BASEMENT].front =
              house[door-BASEMENT].front +
              house[door-BASEMENT].area;
          house[room-BASEMENT].back =
              house[room-BASEMENT].front +
25     house[room-BASEMENT].area -
              (long)4096;
      }

```

The front/back address range marks the storage location in memory 17 in 8-bit data bytes, and thus correlates exactly to a page aligned system address offset. When the system needs to address the memory 17, the driver must know the correct floor to assign since the efficiency and room number are needed to compute the address needed by the memory controller 57 hardware. In order to find the correct floor quickly, the driver maintains a list of screens which have been computed by dividing up the total logical capacity of the device among all the rooms and assigning the appropriate floor to those rooms based on the area consumed by the floor. Thus, a system address is merely divided by the same divisor and used as

the index into the house. The screen value within that entry points to the correct floor. If however, the actual address is greater than the value of the back for that floor, then the room number is simply increased by one.

```

5      repair = (lcap - 4096) / (ATTIC-BASEMENT);
      door = house[BASEMENT-BASEMENT].door;
      start = house[door-BASEMENT].front;
      for (room = BASEMENT-BASEMENT; room < ROOF-
BASEMENT;
10          room++)
      {
          while (((room * repair) + start) >
                (house[door-BASEMENT].back))
              door = house[door-BASEMENT].door;
          house[room].screen = door;
15      }

```

A similar procedure is used whenever the initial transfer did not fit on the floor initially attempted. The compression mechanism 16 returns the actual compressed size in 9-bit ECC bytes. Therefore, the driver need only

20 to divide the value by the size of an ECC block and index to the correct window via the result. The value of the window marks the start of the next accommodating floor.

window sort(ROOF);

```

25      window sort(roof)
          long                roof;
          {
              long            curtain;
              long            window    = BASEMENT;
30              long            room    = BASEMENT;

              while ((room = house[room-BASEMENT].door) !=
BASEMENT)
                  if (window == BASEMENT)
40                      return;
                  curtain = window;
                  while (curtain >= BASEMENT)
                      house[curtain-BASEMENT].window = window;
                  window sort(window);

```

In an alternative embodiment, if the hard disk 14 is used for storing uncompressible pages, all data pages sent via bus 12 for storage may be conditionally stored as uncompressed data on disk 14, while at the same time the page is being compressed in mechanism 26. After the compression operation has been completed then if the level of compression produces a page smaller than the 2800-byte limit or the 2000-byte limit the page is stored again as compressed data in the partition 18 or 19 in the memory 17, and the just-stored page of uncompressed data on the disk 14 is invalidated. Invalidating the uncompressed page merely consists of resetting a bit a page address table in the controller 15 to "empty".

While this invention has been described with reference to specific embodiments, this description is not meant to be construed in a limiting sense. Various modifications of the disclosed embodiments, as well as other embodiments of the invention, will be apparent to persons skilled in the art upon reference to this description. It is therefore contemplated that the appended claims will cover any such modifications or embodiments as fall within the true scope of the invention.

		OUTPUTS																			
		f ₀	f ₁	f ₂	f ₃	f ₄	f ₅	f ₆	f ₇	f ₈	e ₉	e ₁₀	e ₁₁	e ₁₂	e ₁₃	e ₁₄	e ₁₅	e ₁₆	e ₁₇	e ₁₈	
I N P U T S	m ₁ + p ₁₀	1	1	0	1	1	0	1	0	0	1	1	1	1	1	0	1	1	0	1	
	m ₂ + p ₁₁	1	0	1	1	0	1	1	1	0	1	0	0	0	0	1	1	0	1	1	
	m ₃ + p ₁₂	1	0	0	0	0	0	0	1	1	1	0	1	1	1	0	0	0	0	0	
	m ₄ + p ₁₃	0	1	0	0	0	0	0	0	1	1	1	0	1	1	1	0	0	0	0	
	m ₅ + p ₁₄	0	0	1	0	0	0	0	0	0	1	1	1	0	1	1	1	0	0	0	
	m ₆ + p ₁₅	0	0	0	1	0	0	0	0	0	0	1	1	1	1	0	1	1	1	0	0
	m ₇ + p ₁₆	0	0	0	0	1	0	0	0	0	0	0	1	1	1	0	1	1	1	1	0
	m ₈ + p ₁₇	0	0	0	0	0	1	0	0	0	0	0	0	1	1	1	0	1	1	1	1
p ₁₈	1	1	0	1	1	0	0	0	0	0	1	1	1	1	0	1	0	1	1	0	

Table 1. Truth table for circuit M_e of Figure 4.

		outputs ($\alpha^9 p(x)$)									
		q_8	q_7	q_6	q_5	q_4	q_3	q_2	q_1	q_0	
I N P U T S	p_8	1	1	0	0	0	1	0	0	0	α^{17}
	p_7	0	1	1	0	0	0	1	0	0	α^{16}
	p_6	0	0	1	1	0	0	0	1	0	α^{15}
	p_5	0	0	0	1	1	0	0	0	1	α^{14}
	p_4	1	0	0	0	1	0	0	0	0	α^{13}
	p_3	0	1	0	0	0	1	0	0	0	α^{12}
	p_2	0	0	1	0	0	0	1	0	0	α^{11}
	p_1	0	0	0	1	0	0	0	1	0	α^{10}
	p_0	0	0	0	0	1	0	0	0	1	α^9

Table 2. Truth table of circuit M_1 for S_1 calculator of Figure 7b. (Output $q_8 = p_4 + p_8$.) Circuit multiplies its input 9-tuple by α^9 .

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		outputs $a^{27}p(x)$								
		q_8	q_7	q_6	q_5	q_4	q_3	q_2	q_1	q_0
	p_8	1	0	1	1	0	1	0	1	0 a^{35}
I	p_7	0	1	0	1	1	0	1	0	1 a^{34}
N	p_6	1	0	1	0	1	0	0	1	0 a^{33}
P	p_5	0	1	0	1	0	1	0	0	1 a^{32}
U	p_4	1	0	1	0	1	1	1	0	0 a^{31}
T	p_3	0	1	0	1	0	1	1	1	0 a^{30}
S	p_2	0	0	1	0	1	0	1	1	1 a^{29}
$p(x)$	p_1	1	0	0	1	0	0	0	1	1 a^{28}
	p_0	1	1	0	0	1	1	0	0	1 a^{27}

Table 3a. Truth table of circuit M_3 for S_3 calculator of Figure 9. (Output $q_8 = p_0 + p_1 + p_4 + p_6 + p_8$.)
Circuit multiplies its input 9-tuple by a^{27} .

		outputs $r(a^3)$								
		t_8	t_7	t_6	t_5	t_4	t_3	t_2	t_1	t_0
	r_8	0	0	1	1	1	0	0	0	1 a^{24}
I	r_7	0	0	1	0	0	1	1	0	0 a^{21}
N	r_6	1	0	0	0	0	0	0	0	1 a^{18}
P	r_5	0	0	1	1	0	0	0	1	0 a^{15}
U	r_4	0	1	0	0	0	1	0	0	0 a^{12}
T	r_3	0	0	0	0	1	0	0	0	1 a^9
S	r_2	0	0	1	0	0	0	0	0	0 a^6
	r_1	0	0	0	0	0	1	0	0	0 a^3
	r_0	0	0	0	0	0	0	0	0	1 a^0

Table 3b. Truth table of circuit M_0 for S_3 calculator of Figure 9. Output $t_5 = r_8 + r_5$.

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Number of Cycles	Register Contents	
	F	G
0	0	0
1	S_1^2	
2	S_1^4	S_1^3
3	S_1^8	S_1^7
4	S_1^{16}	S_1^{15}
5	S_1^{32}	S_1^{31}
6	S_1^{64}	S_1^{63}
7	S_1^{64}	S_1^{127}
8	S_1^{254}	S_1^{127}
9	S_1^{508}	S_1^{127}
10	S_1^{508}	$S_3 \cdot S_1^{508}$

Table 4. Steps involved in computing $S_3 S_1^{-3}$.

S_0	Number of errors corrected	Error Count $C_1 C_0$	Uncorrectable Error Detected
0	0	0 0	No
0	1	0 1	Yes
0	2	1 0	No
1	0	0 0	Yes
1	1	0 1	No
1	2	1 0	Yes

Table 6. Cases under which an uncorrectable error is detected by inconsistency between S_0 and Number of Errors Corrected.

0	1	0	0	0	0	0	0	0
0	0	1	0	0	0	0	0	0
0	0	0	1	0	0	0	0	0
0	0	0	0	1	0	0	0	0
1	0	0	0	0	1	0	0	0
0	0	0	0	0	0	1	0	0
0	0	0	0	0	0	0	1	0
0	0	0	0	0	0	0	0	1
1	0	0	0	0	0	0	0	0

21

1	0	0	0	0	1	0	0	0
0	1	0	0	0	0	1	0	0
0	0	1	0	0	0	0	1	0
0	0	0	1	0	0	0	0	1
1	0	0	0	1	0	0	0	0
0	1	0	0	0	0	0	0	0
0	0	1	0	0	0	0	0	0
0	0	0	1	0	0	0	0	0
0	0	0	0	1	0	0	0	0

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0	0	1	0	0	0	0	0	0
0	0	1	0	0	0	0	0	0
0	0	0	0	1	0	0	0	0
1	0	0	0	0	1	0	0	0
0	1	0	0	0	0	1	0	0
0	0	0	0	0	0	0	1	0
0	0	0	0	0	0	0	0	1
1	0	0	0	0	0	0	0	0
0	1	0	0	0	0	0	0	0

 σ^2

0	0	1	0	0	0	0	1	0	0
0	0	1	1	0	0	0	0	1	0
0	0	0	0	1	0	0	0	0	1
1	0	0	0	0	1	0	0	0	0
1	1	0	0	0	0	1	0	0	0
0	0	1	0	0	0	0	0	0	0
0	0	0	1	0	0	0	0	0	0
0	0	0	0	1	0	0	0	0	0
1	0	0	0	0	1	0	0	0	0

6

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 1 \end{bmatrix}$$

g 502

0	0	0	1	0	0	0	0	0
0	0	0	0	1	0	0	0	0
0	1	0	0	0	0	1	0	0
0	0	1	0	0	0	0	1	0
0	0	0	1	0	0	0	0	1
0	0	0	0	0	0	0	0	0
0	1	0	0	0	0	0	0	0
0	0	1	0	0	0	0	0	0
0	0	1	0	0	0	0	0	0

3

0	0	1	0	0	0	0	1	0
0	0	0	1	0	0	0	0	1
1	0	0	0	1	0	0	0	0
1	1	0	0	0	1	0	0	0
0	1	1	0	0	0	1	0	0
0	0	0	1	0	0	0	0	0
0	0	0	0	1	0	0	0	0
1	0	0	0	0	1	0	0	0
0	1	0	0	0	0	1	0	0

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0	0	0	0	1	0	0	0	0
1	0	0	0	0	1	0	0	0
0	1	0	0	0	0	1	0	0
0	0	1	0	0	0	0	1	0
0	0	0	1	0	0	0	0	1
1	0	0	0	0	0	0	0	0
0	1	0	0	0	0	0	0	0
0	0	1	0	0	0	0	0	0
0	0	0	1	0	0	0	0	0

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0	0	0	1	0	0	0	0	1
1	0	0	0	1	0	0	0	0
1	1	0	0	0	1	0	0	0
0	1	1	0	0	0	1	0	0
0	0	1	1	0	0	0	1	0
0	0	0	0	1	0	0	0	0
1	0	0	0	0	1	0	0	0
0	1	0	0	0	0	1	0	0
0	0	1	0	0	0	0	1	0

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Table 5.

Matrices for fixed-element multipliers for Mapper Circuit of Figure 10. For $B = a^1A$, $b_8 = a_7$, $b_4 = a_8 + a_3$ and $b_0 = a_8$.

CLAIMS:

1. A method of storing pages of compressed data in a semiconductor memory, the pages of data being of fixed size before compression,
5 comprising the steps of:

a) partitioning the semiconductor memory to provide first and second memory spaces, each of said memory spaces containing a large number of memory locations, the memory locations of the first memory space being of a first size for storing one of said pages of data compressed to at most said
10 first size, the memory locations of the second memory space being of a second size for storing one of said pages of data compressed to at most said second size;

b) receiving and compressing each of said pages of data to produce a compressed page, and detecting whether or not each said compressed page
15 is as small as said first size or said second size;

c) storing each of said pages of data in either said first or second memory space in response to said step of detecting, or, if said page is not compressed to as small as said first or second size, storing said page uncompressed in a third memory space.

20

2. A method according to claim 1 wherein said first and second memory spaces are larger than said third memory space.

3. A method according to claim 2 wherein said fixed size is about
25 twice as large as said first size, and wherein said second size is smaller than said fixed size and larger than said first size.

4. A method according to claim 1 including the steps of providing a separate address for each of said pages and storing said address in a table
30 associating a location of a page in said first or second memory spaces.

5. A method according to claim 4 including the step of recalling one of said pages of data by

d) receiving a request for said one of said pages using said address for said page;

5 e) reading said page from said first or second memory space using said address;

f) decompressing said page.

6. A method according to claim 1 including the step of generating an
10 ECC code for each of a plurality of blocks of each of said compressed pages, and wherein said step of storing includes storing said ECC codes with said compressed pages.

7. A method according to claim 6 wherein said compressed pages
15 are transferred as parallel 9-bit symbols to said step of generating an ECC code, and wherein said blocks are transferred to said step of storing as parallel 9-bit symbols.

8. A memory device for storing pages of data, the pages of data
20 being of fixed size, comprising:

a) a first memory space in said memory device containing a large number of memory locations of a first size, each of said memory locations of a first size storing a compressed version of one of said pages of data;

25 b) a second memory space in said memory device containing a large number of memory locations of a second size larger than said first size but smaller than said fixed size, each of said memory locations of said second size storing a compressed version of one of said pages of data;

c) means for compressing each of said pages of data to produce a compressed page, and means for detecting whether or not each said
30 compressed page is as small as said first size or if not then as small as said second size;

d) and means for storing each of said pages of data in either said first memory space or said second memory space in response to said means for detecting.

5 9. A memory device according to claim 8 wherein said first and second memory spaces are defined in semiconductor memory.

10 10. A memory device according to claim 9 wherein said fixed size is about twice as large as said first size; and wherein said second size is about 70% as large as said fixed size.

15 11. A memory device according to claim 8 including means for receiving a separate address with each of said pages and storing said address in said memory device associated with a location of said page in said first or second memory spaces.

12. A memory device according to claim 11 including means for recalling said data pages, including:

20 e) means for receiving a request for one of said pages including said address for said page;

f) means for finding said address for said page in said stored addresses and determining the location of said page;

25 g) means for detecting whether or not said page was stored in said first or second memory space, and, if so, decompressing said page.

13. A memory device according to claim 8 including means for generating an ECC code for each of a plurality of blocks of each of said compressed pages, and wherein said means for storing stores said ECC codes with said compressed pages; and including means for transferring said 30 compressed pages as parallel 9-bit symbols to said means for generating an

ECC code, and wherein said blocks are transferred to said means for storing as parallel 9-bit symbols.

5 14. A memory device according to claim 8 wherein said means for compressing includes a lookahead buffer number of bytes of incoming data, and a window buffer containing a larger number of bytes of recent incoming data, and means for comparing the bytes in said lookahead buffer to all of the bytes in said window buffer and generating match symbols if multiple-byte matches are found in said comparing.

10

15 15. A memory device according to claim 14 wherein said lookahead buffer and said window buffer are of bit-parallel format, and the output of said means for compressing includes an added bit that indicates whether or not an output of the means for compressing represents a compressed or non-compressed symbol.

16. A method of storing page-swap data in a virtual memory system, comprising the steps of:

20 storing in a semiconductor memory unit a large number of swap pages either (a) compressed to a level no more than a first value and stored in a first area of said memory, or (b) compressed to a level no more than a second value but greater than said first value and stored in a second area of said memory, or (c) if not compressible to said second value or less then stored uncompressed in a third area of said memory;

25 recording the number of pages stored in each of said first, second and third areas;

30 partitioning said memory in response to said recorded numbers to provide boundaries between said first, second and third areas defined by addresses, to thereby again store said page-swap data in a minimum of space in said memory; each said partitions defining memory blocks of said first value, said second value or the size of said pages.

17. A method according to claim 16 wherein said first and second memory areas are larger than said third memory area; and wherein said pages are of a fixed size about twice as large as said first value, and wherein said second value is smaller than said fixed size and larger than said first value.

18. A method according to claim 16 including the steps of providing a separate address for each of said pages and storing said address in a table associating a location of a page in said first or second memory areas; and further including the step of recalling one of said pages of data by

- a) receiving a request for said one of said pages using said address for said page;
- b) reading said page from said first or second memory areas using said address;
- c) decompressing said page.

19. A method according to claim 16 including the step of generating an ECC code for each of a plurality of blocks of each of said compressed pages, and wherein said step of storing includes storing said ECC codes with said compressed pages.

20. A method according to claim 19 wherein said compressed pages are transferred as parallel 9-bit symbols to said step of generating an ECC code, and wherein said blocks are transferred to said step of storing as parallel 9-bit symbols.

21. A method of storing blocks of data in a memory device, the blocks of data being of fixed size, comprising the steps of:

- a) partitioning the memory device to provide a first memory space containing a large number of memory locations of a first size for storing a compressed version of one of said blocks of data, and to provide a second

memory space containing a large number of memory locations of said fixed size for storing an uncompressed version of one of said blocks of data;

b) receiving and compressing each of said blocks of data to produce a compressed block, and detecting whether or not each said compressed
5 block is as small as said first size;

c) storing each of said blocks of data in either said first memory space or said second memory space in response to said step of detecting.

22. A method according to claim 21 wherein said memory device is
10 a magnetic disk.

23. A method according to claim 22 wherein said first memory space is a first partition of said disk and said second memory space is a second partition of said disk.
15

24. A method according to claim 23 wherein said first partition is much larger than said second partition.

25. A method according to claim 24 wherein said fixed size is about
20 twice as large as said first size.

26. A method according to claim 21 including the steps of receiving a separate address with each of said blocks and storing said address in said memory device associated with a location of said block in said first or
25 second memory spaces.

27. A method according to claim 26 including the step of recalling said data blocks by

d) receiving a request for one of said blocks using said address for
30 said block;

e) finding said address for said block in said stored addresses and determining the location of said block;

f) detecting whether or not said block was stored in said first memory space; and

5 g) decompressing said block if stored in said first memory space.

28. A memory device for storing blocks of data, the blocks of data being of fixed size, comprising:

10 a) a first memory space in said memory device containing a large number of memory locations of a first size, each of said memory locations of a first size storing a compressed version of one of said blocks of data;

b) a second memory space in said memory device containing a large number of memory locations of said fixed size, each of said memory locations of said fixed size storing an uncompressed version of one of said
15 blocks of data;

c) means for compressing each of said blocks of data to produce a compressed block, and means for detecting whether or not each said compressed block is as small as said first size;

d) and means for storing each of said blocks of data in either said
20 first memory space or said second memory space in response to said means for detecting.

29. A memory device according to claim 28 wherein said first and second memory spaces are defined in a magnetic disk.

25

30. A memory device according to claim 29 wherein said first memory space is much larger than said second memory space.

31. A memory device according to claim 30 wherein said fixed size is
30 about twice as large as said first size.

32. A memory device according to claim 28 including means for receiving a separate address with each of said blocks and storing said address in said memory device associated with a location of said block in said first or second memory spaces.

5

33. A memory device according to claim 32 including means for recalling said data blocks, including:

e) means for receiving a request for one of said blocks including said address for said block;

10 f) means for finding said address for said block in said stored addresses and determining the location of said block;

g) means for detecting whether or not said block was stored in said first memory space; and

15 h) means for decompressing said block if stored in said first memory space.

34. A digital system comprising:

a) a source of data blocks of fixed length;

20 b) storage means having first storage locations of a selected size less than said fixed length and second storage locations of said fixed length;

c) a data compression unit receiving said data blocks from said source and compressing each of said data blocks to produce a compressed block;

25 d) and means for storing a compressed block in one of said first storage locations if said compressed block is as small as said selected size, or for storing data for one of said data blocks in one of said second locations if said compressed block is larger than said selected size.

30 35. A system according to claim 34 wherein said first and second storage locations are defined in a magnetic disk.

36. A system according to claim 35 wherein said storage locations occupy a first memory space which is much larger than a second memory space occupied by said second storage locations.

5 37. A system according to claim 36 wherein said fixed size is about twice as large as said selected size.

38. A system according to claim 34 including means for receiving a separate address with each of said blocks and storing said address in said
10 storage means associated with one of said first or second storage locations.

39. A system according to claim 38 including means for recalling said data blocks, including:

15 e) means for receiving a request for one of said blocks including said address for said block;

 f) means for finding said address for said block in said stored addresses and determining the location of said block;

 g) means for detecting whether or not said block was stored in one of said first storage locations; and

20 h) means for decompressing said block if stored in one of said first storage locations.

40. A system according to claim 34 wherein said storage means includes third storage locations of a third size less than said selected size;
25 and said means for storing stores a compressed block in said third storage location if said compressed block is as small as said third size.

41. A system according to claim 34 wherein said first storage locations are defined in semiconductor memory and said second storage
30 locations are defined in a magnetic disk.

42. A memory system storing blocks of data of fixed size,
comprising:

a) a first memory space containing memory locations of a first size,
each of said memory locations of a first size storing a compressed version of
5 one of said blocks of data;

b) a second memory space containing memory locations of said fixed
size, each of said memory locations of said fixed size storing an
uncompressed version of one of said blocks of data;

c) a third memory space containing a table of the locations of blocks
10 of data in said first and second memory spaces;

d) means for receiving a request for one of said blocks including an
identification of said block;

f) means for finding said identification in said third memory space
and determining the location of said block in said first or second memory
15 space;

g) means for detecting if said block was stored in said first memory
space, and if so decompressing said block.

43. A memory device according to claim 42 wherein said first and
20 second memory spaces are defined in a magnetic disk.

44. A memory device according to claim 42 wherein said first
memory space is constructed of semiconductor memory devices and said
second memory space is defined in a magnetic disk device.

25

45. A memory device according to claim 42 wherein said first and
second memory spaces are defined in semiconductor memory devices of the
non-volatile type.

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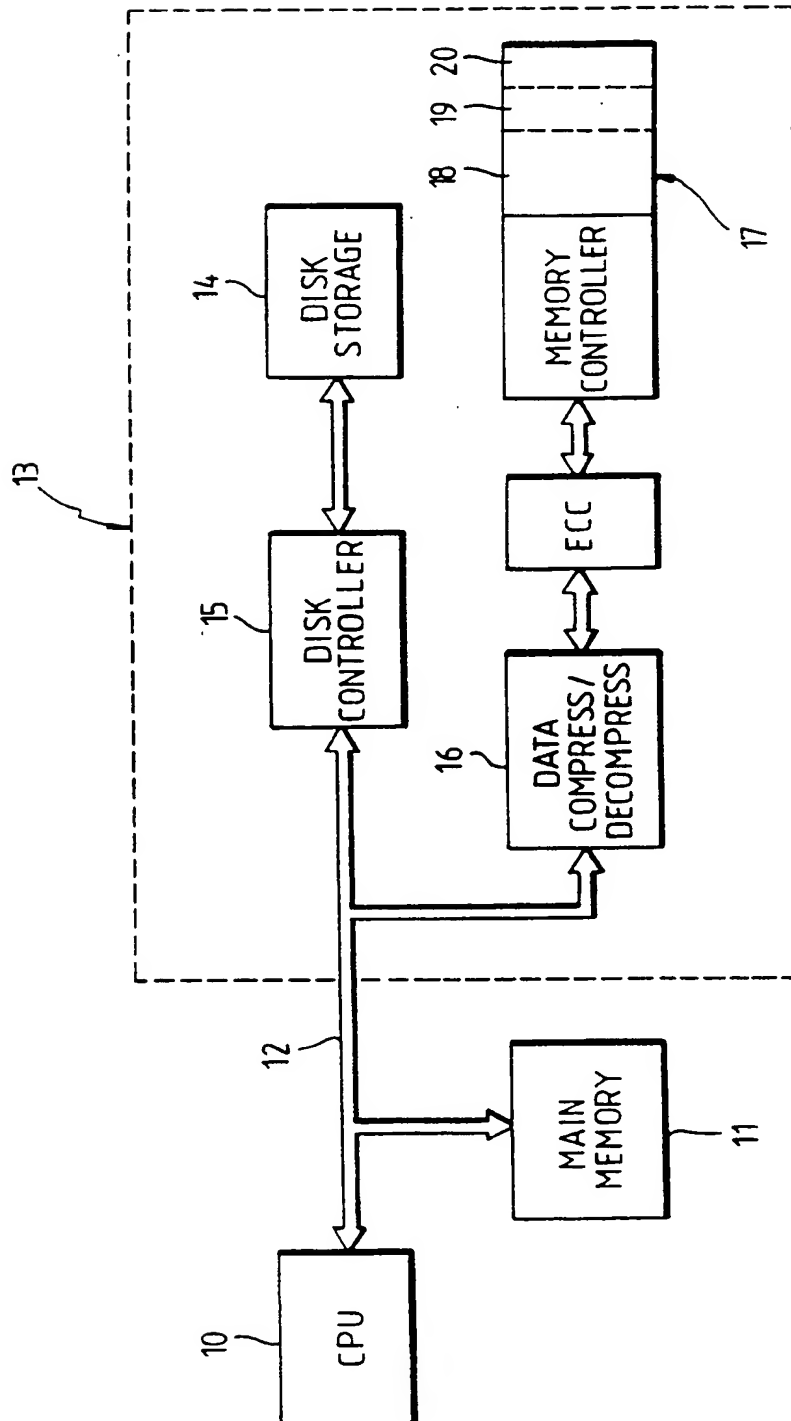


FIG. 1

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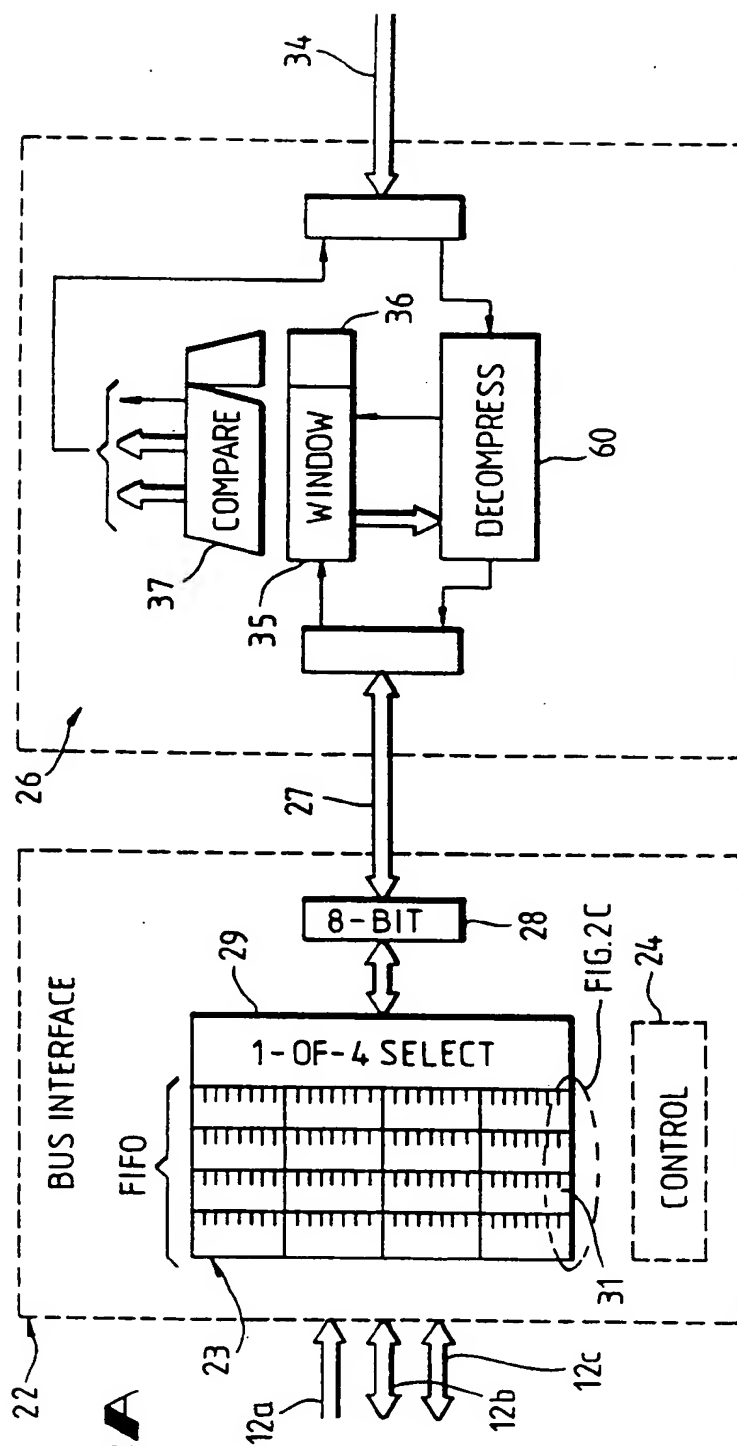


FIG. 2A

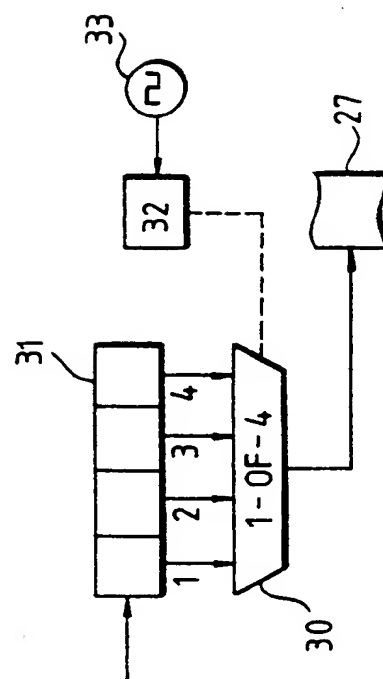


FIG. 21

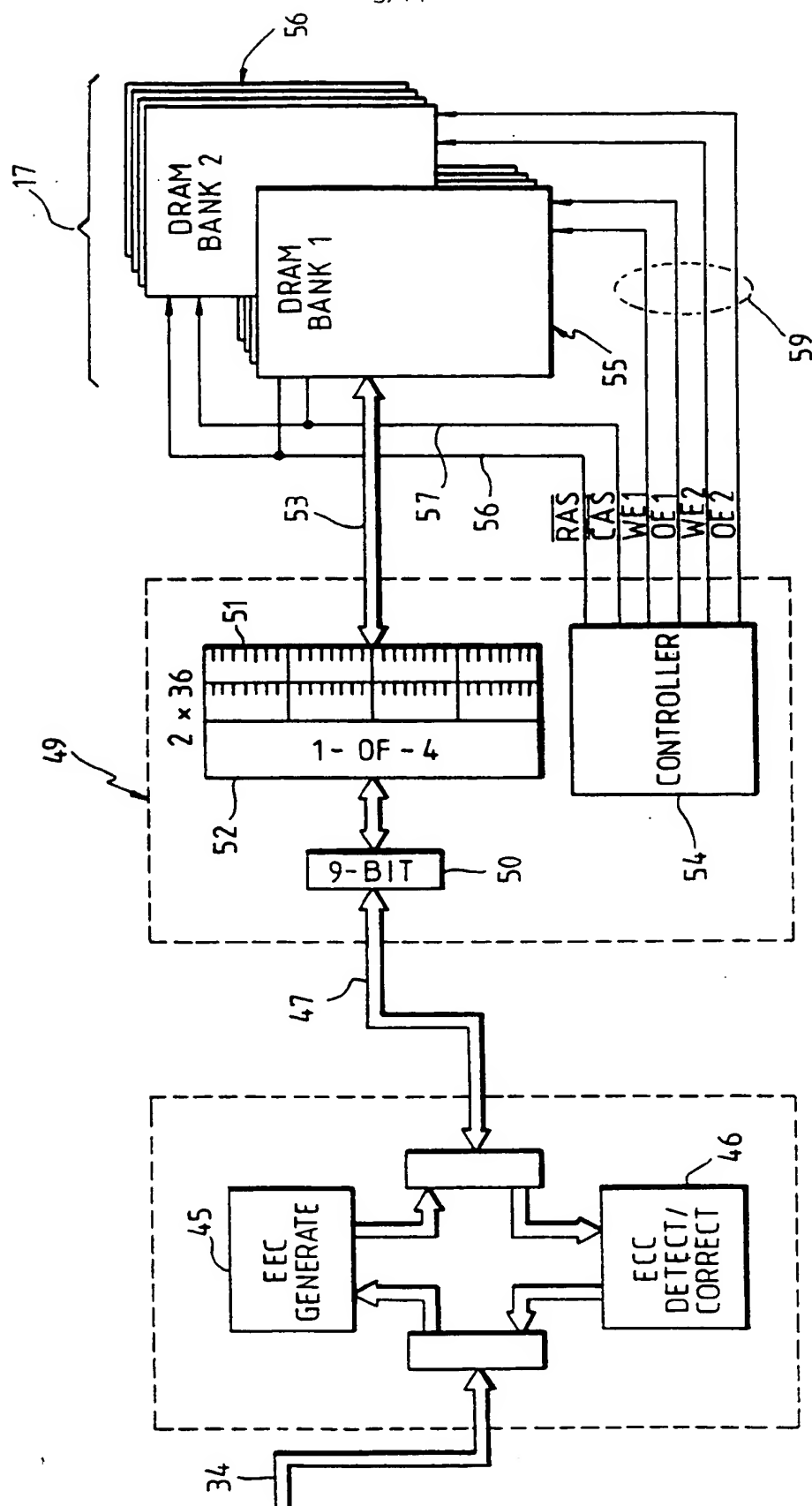


FIG. 2B

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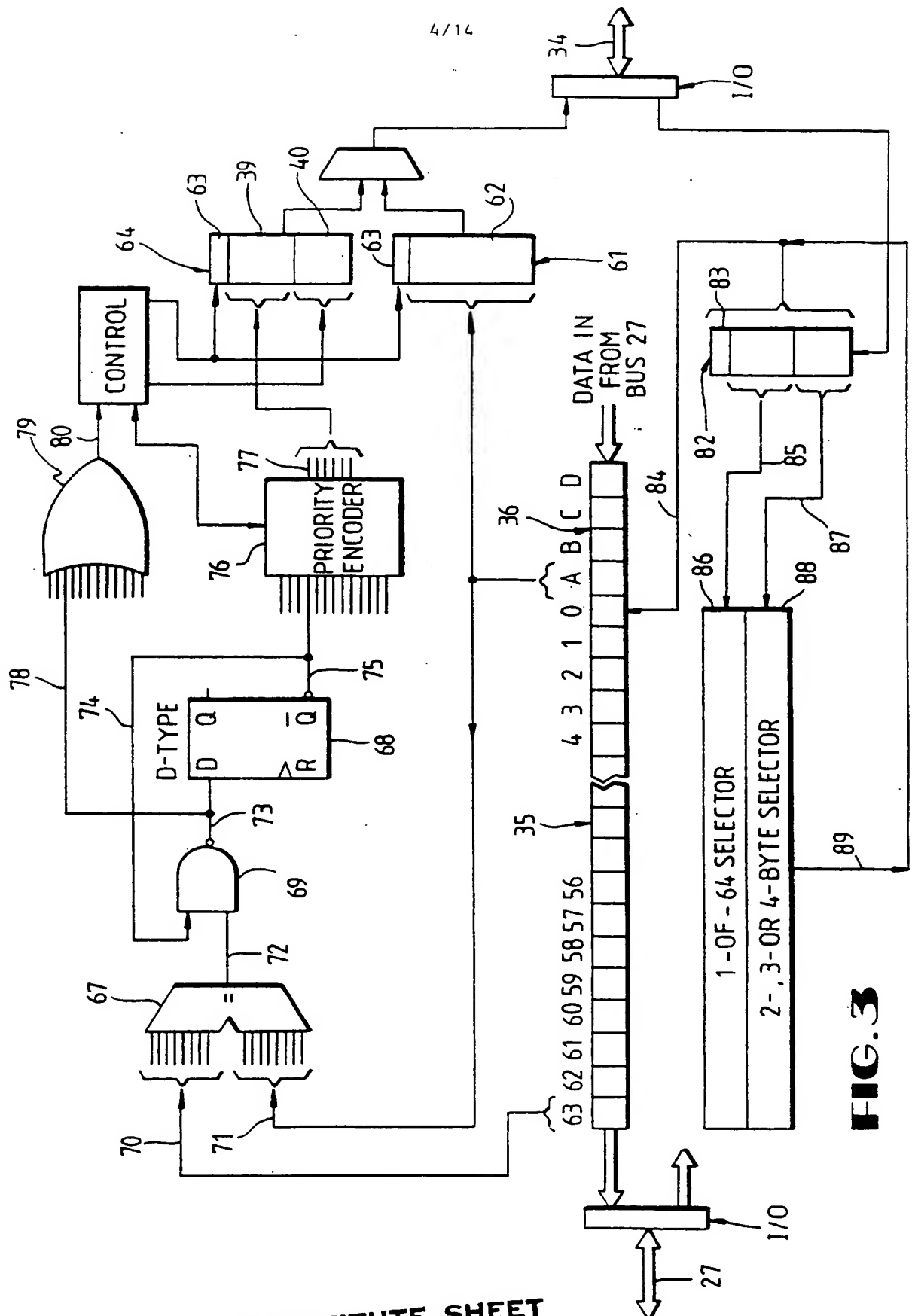


FIG. 3

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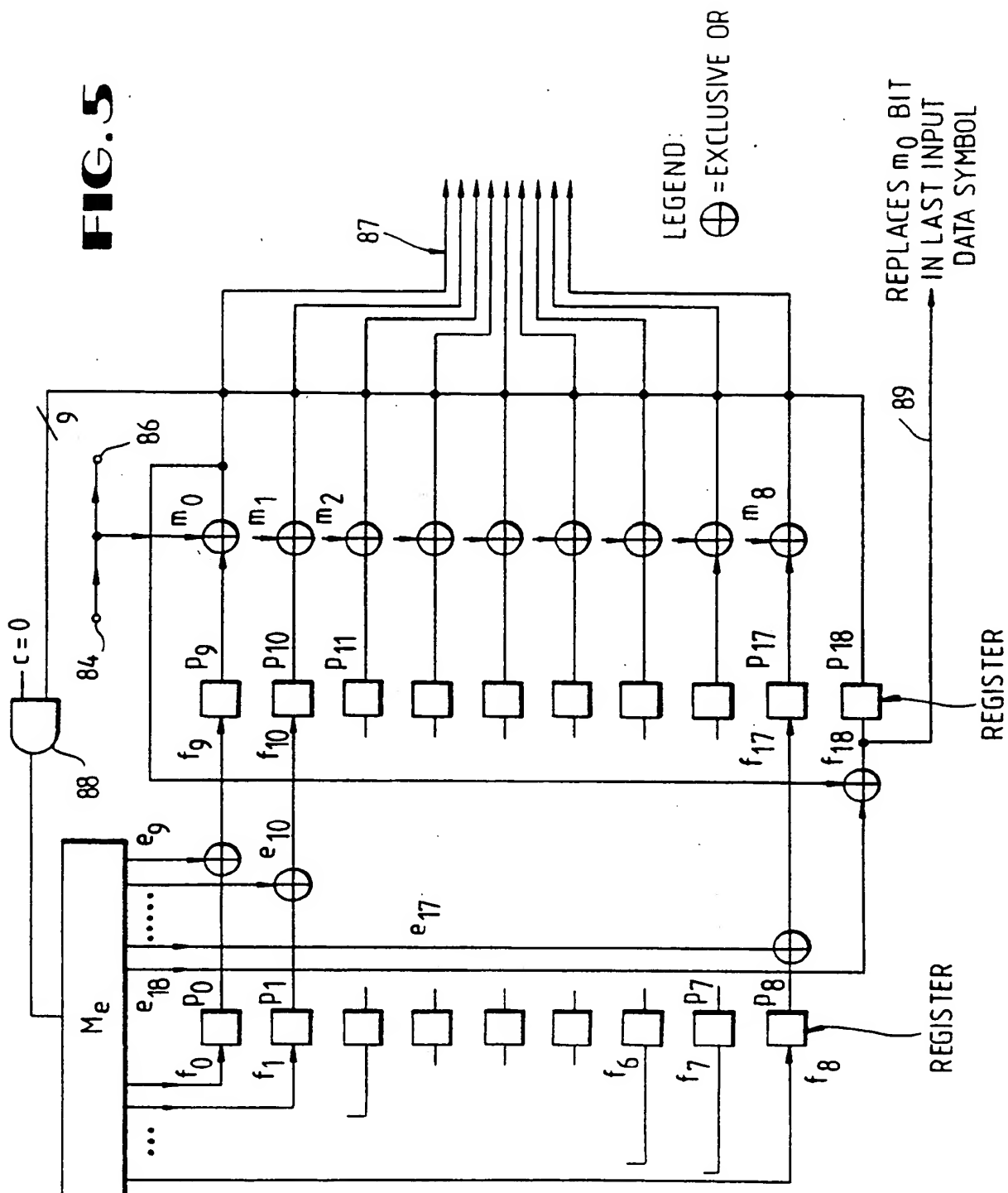
FIG.4

CLK	WINDOW BUFFER				LOOK AHEAD BUFFER	HEX OUT	MATCH
1	00000000	00000000	00000000	00000000	THIS	054	NO
2	00000000	00000000	00000000	0000000T	HIS_	048	NO
3	00000000	00000000	00000000	000000TH	IS_I	049	NO
4	00000000	00000000	00000000	00000THI	S_IS	053	NO
5	00000000	00000000	00000000	0000THIS	_IS_	05F	NO
6	00000000	00000000	00000000	000THIS	IS_T	10A	YES-3
7	00000000	00000000	00000000	00THIS_I	S_TE	---	--
8	00000000	00000000	00000000	0THIS_IS	_TES	---	--
9	00000000	00000000	00000000	THIS_IS_	TEST	054	NO
10	00000000	00000000	0000000T	HIS_IS_T	EST_	045	NO
11	00000000	00000000	000000TH	IS_IS_TE	ST_A	053	NO
12	00000000	00000000	00000THI	S_IS_TES	T_A_	054	NO
13	00000000	00000000	0000THIS	_IS_TEST	_A_	05F	NO
14	00000000	00000000	000THIS_	IS_TEST_	A_T	041	NO
15	00000000	00000000	00THIS_I	S_TEST_A	_TH	05F	NO
16	00000000	00000000	0THIS_IS	_TEST_A_	_THI	11D	YES-2
17	00000000	00000000	THIS_IS_	TEST_A_	THIS	---	--
18	00000000	0000000T	HIS_IS_T	EST_A_T	HIS_	13F	YES-4
19	00000000	000000TH	IS_IS_TE	ST_A_TH	IS_I	---	--
20	00000000	00000THI	S_IS_TES	T_A_THI	S_IS	---	--
21	00000000	0000THIS	_IS_TEST	_A_THIS	_IS_	---	--
22	00000000	000THIS_	IS_TEST_	A_THIS_	IS_T	13F	YES-4
23	00000000	00THIS_I	S_TEST_A	_THIS_I	S_TE	---	--
24	00000000	0THIS_IS	_TEST_A_	_THIS_IS	_TES	---	--
25	00000000	THIS_IS_	TEST_A_	THIS_IS_	TEST	---	--
26	0000000T	HIS_IS_T	EST_A_T	HIS_IS_T	EST_	13F	--
27	000000TH	IS_IS_TE	ST_A_TH	IS_IS_TE	ST_B	---	--
28	00000THI	S_IS_TES	T_A_THI	S_IS_TES	T_B_	---	--
29	0000THIS	_IS_TEST	_A_THIS	_IS_TEST	_B_	---	--
30	000THIS_	IS_TEST_	A_THIS_	IS_TEST_	B_T	042	NO
31	00THIS_I	S_TEST_A	_THIS_I	S_TEST_B	_TH	13F	YES-4
32	0THIS_IS	_TEST_A_	_THIS_IS	_TEST_B_	_THI	---	--
33	THIS_IS_	TEST_A_	THIS_IS_	TEST_B_	THIS	---	--
34	HIS_IS_T	EST_A_T	HIS_IS_T	EST_B_T	HIS	---	--
35	IS_IS_TE	ST_A_TH	IS_IS_TE	ST_B_TH	IS	131	YES-2
36	S_IS_TES	T_A_THI	S_IS_TES	T_B_THI	S	---	--

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FIG. 5.



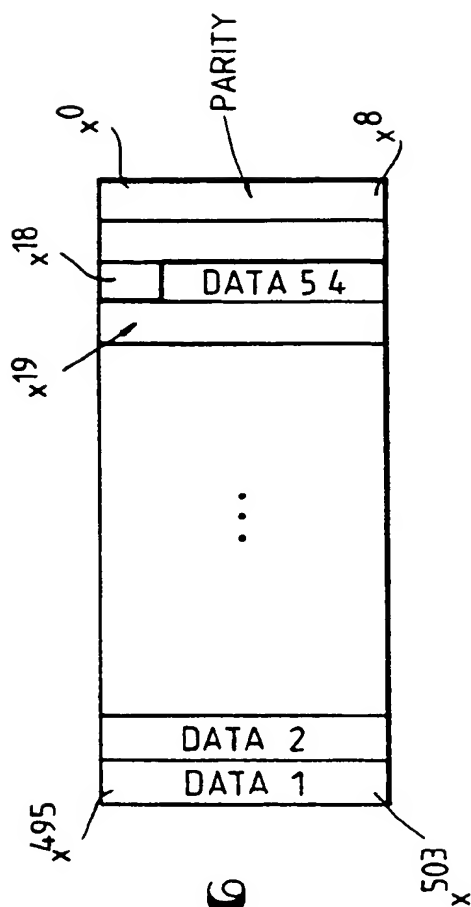


FIG. 6

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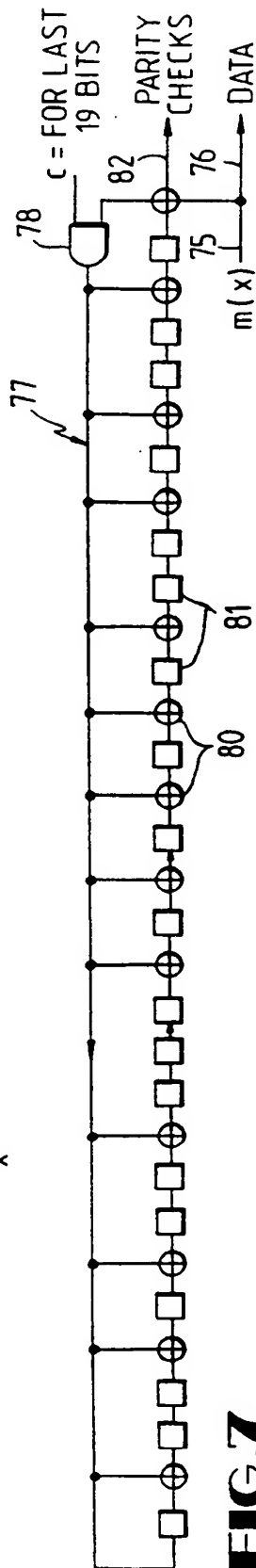


FIG. 7

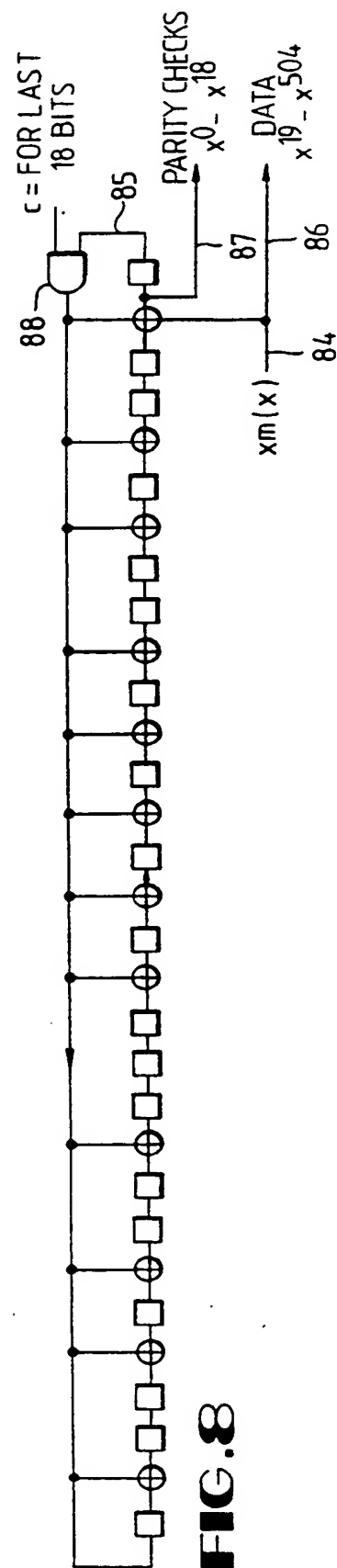
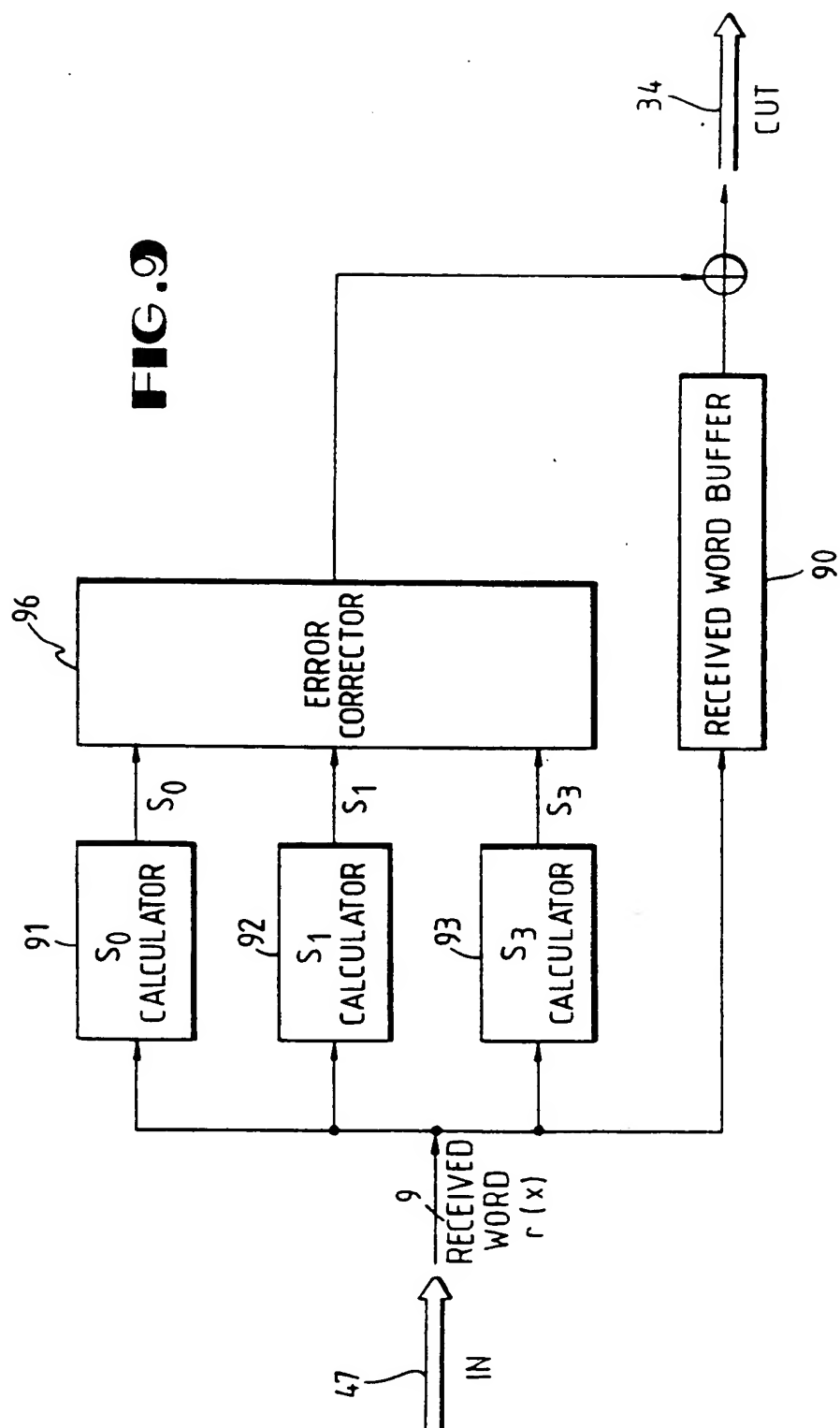


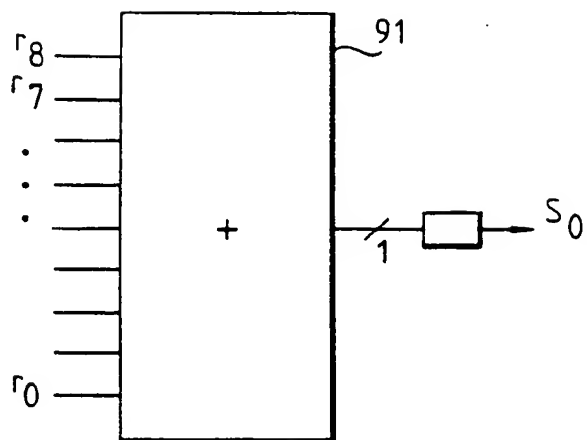
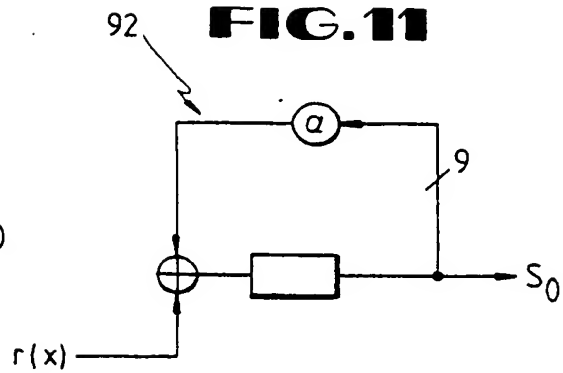
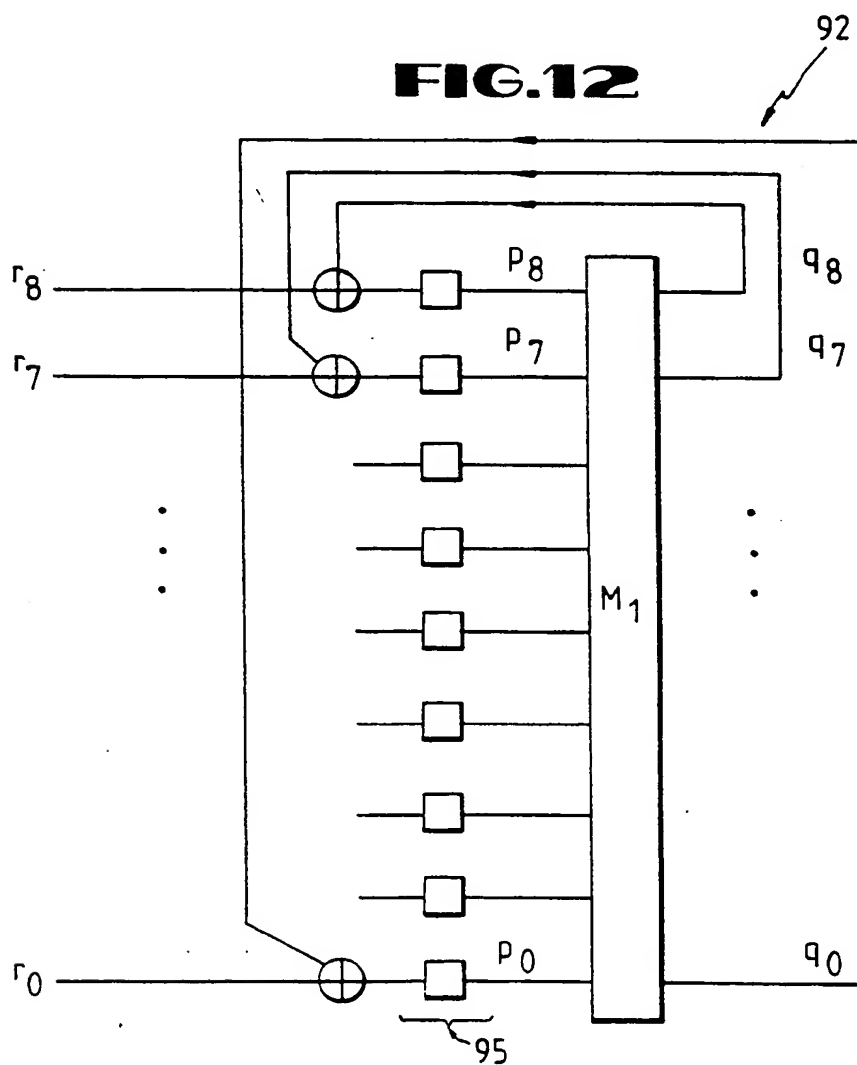
FIG. 8

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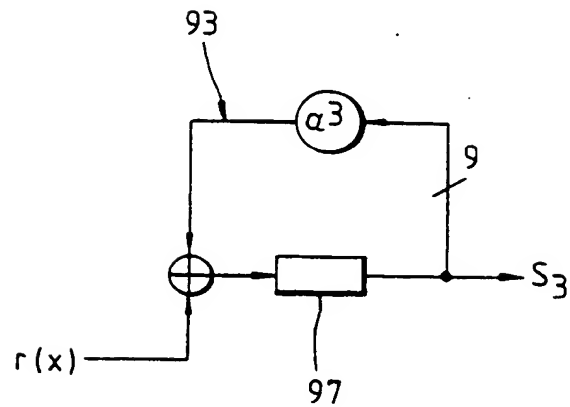
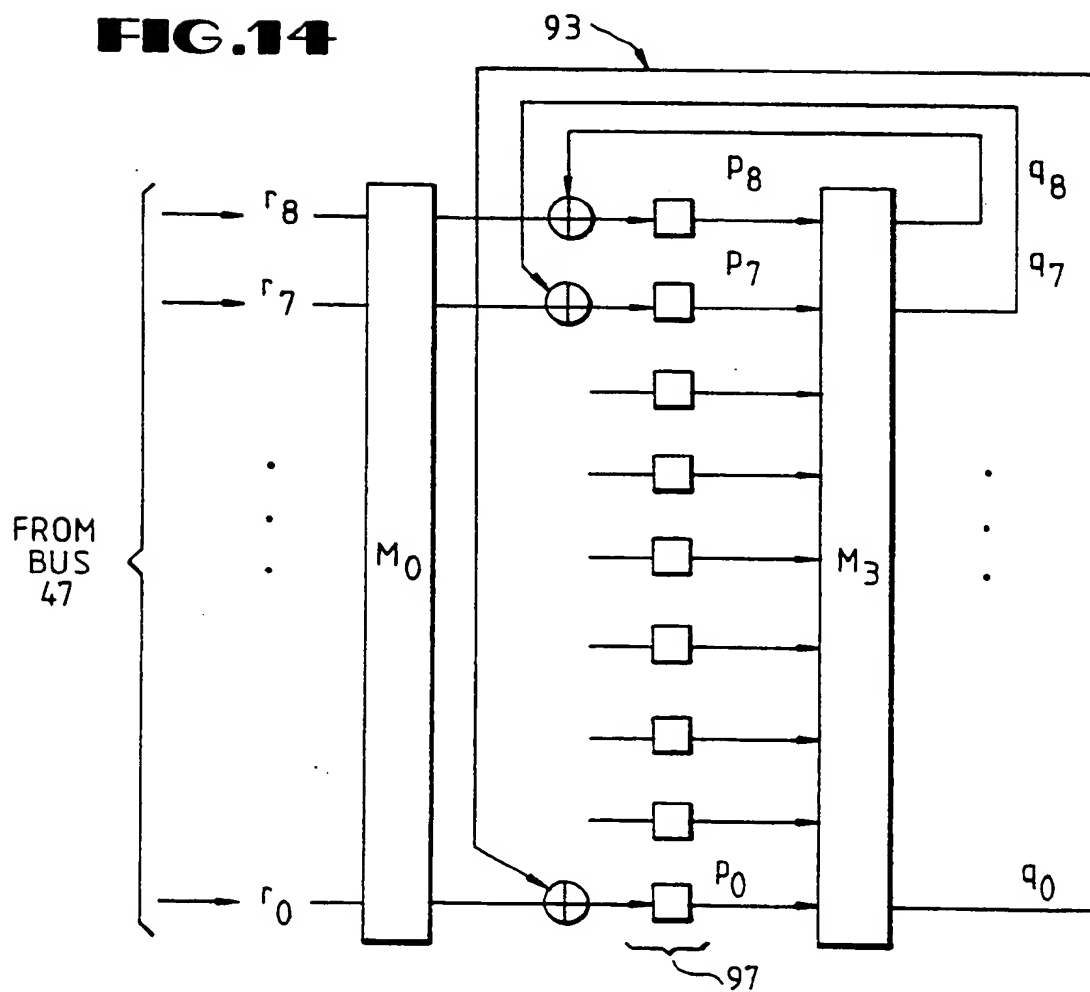
FIG. 9

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FIG.10**FIG.11****FIG.12****SUBSTITUTE SHEET**

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FIG.13**FIG.14**

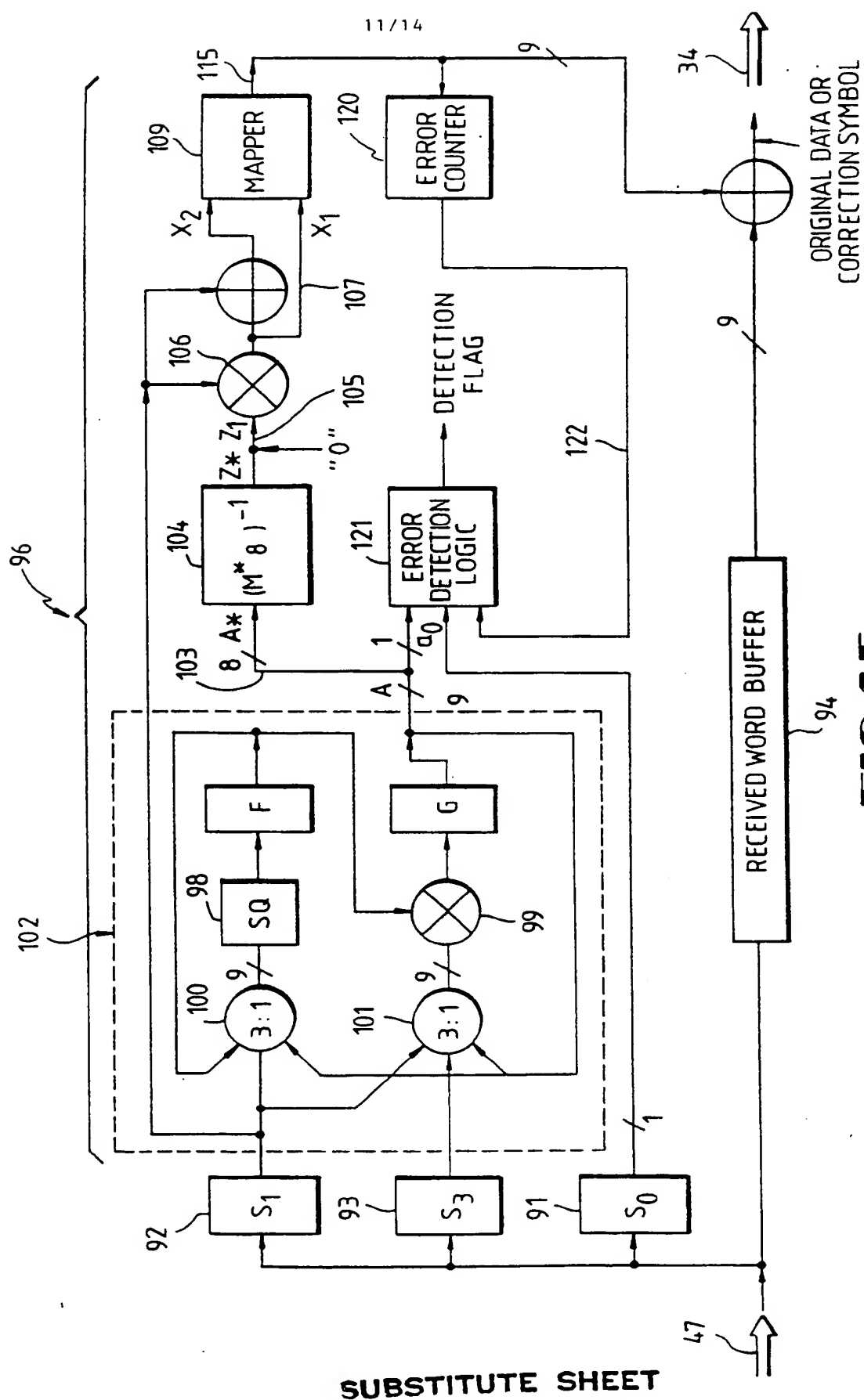


FIG. 15

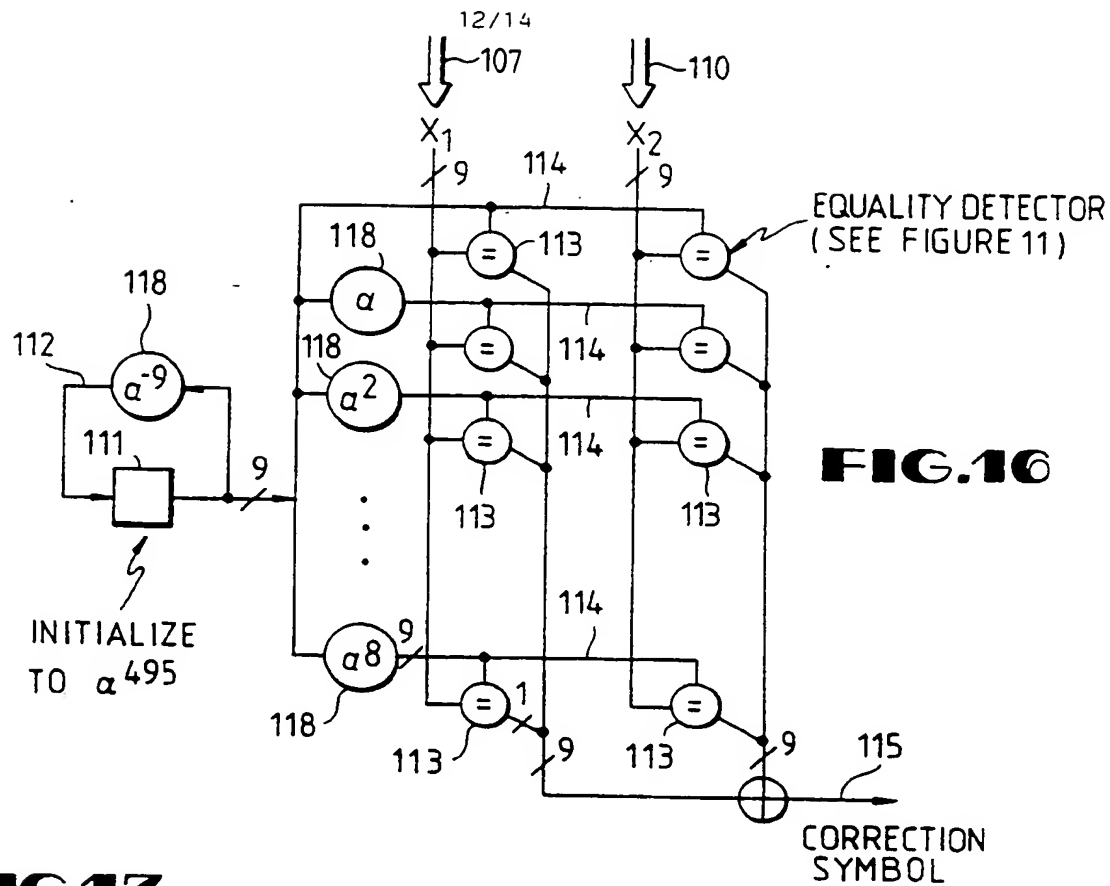
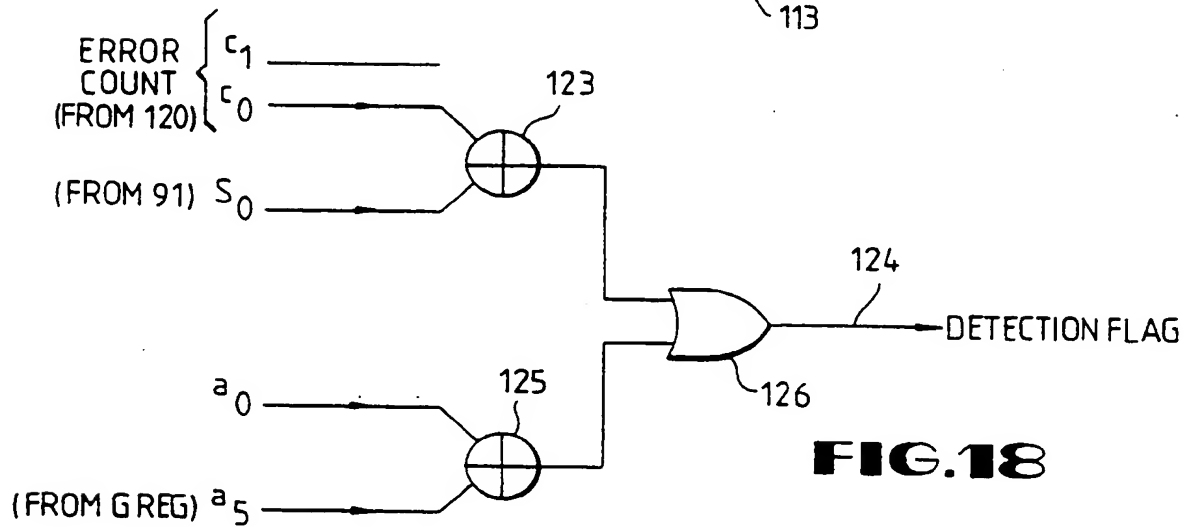
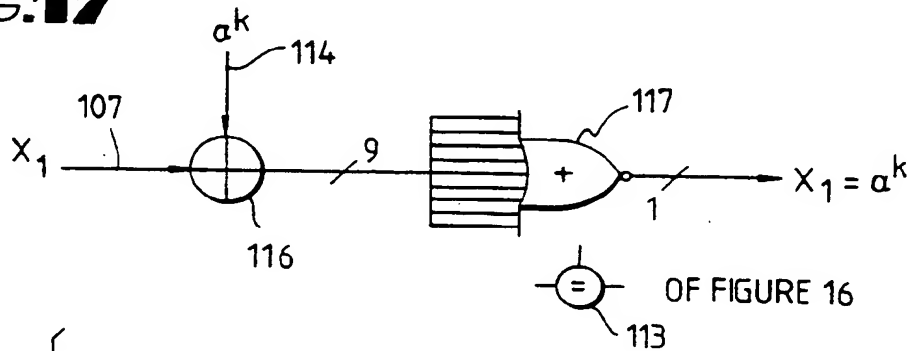


FIG. 17



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FIG.19

	DOOR	POP	CAP	EFF	FRONT	BACK	SCREEN	WINDOW
20	24							
21								
22								
23								
24	36	0.305						
25								
26								
27								
35	46	0.415						
36								
37								
45	65	0.234						
46								
47								
63								
64								
65	20	0.037						

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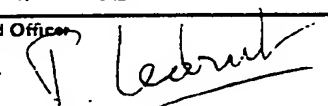
DOOR POP	CAP	EFF	FRONT	BACK	SCREEN WINDOW
20	36				24
21					24
22					24
23					24
24	0.305	0.369	32329728	56082432	24
25					36
26					36
27					36
35	24	0.415	0	32325632	36
36		0.554			36
37					46
38					46
39					46
45	65	0.234	56086528	74309632	46
46		0.166			46
47					65
48					65
49					65
50					65
51					65
52					65
53					65
62					65
63					65
64					65
65	20	0.037	74313728	77189120	65

FIG.20**SUBSTITUTE SHEET**

INTERNATIONAL SEARCH REPORT

International Application No.

PCT/US 92/02364

I. CLASSIFICATION OF SUBJECT MATTER (If several classification symbols apply, indicate all) ⁶		
According to International Patent Classification (IPC) or to both National Classification and IPC Int.Cl. 5 G06F12/02		
II. FIELDS SEARCHED		
Minimum Documentation Searched ⁷		
Classification System	Classification Symbols	
Int.Cl. 5	G06F	
Documentation Searched-other than Minimum Documentation to the Extent that such Documents are Included in the Fields Searched ⁸		
III. DOCUMENTS CONSIDERED TO BE RELEVANT⁹		
Category ¹⁰	Citation of Document, ¹¹ with indication, where appropriate, of the relevant passages ¹²	Relevant to Claim No. ¹³
A	WO,A,8 002 610 (TELXON) 27 November 1980 see abstract see page 2, line 10 - page 4, line 14 ---	1
A	COMPUTER ARCHITECTURE NEWS. vol. 19, no. 2, April 1991, IEEE, WASHINGTON D.C., US pages 96 - 107; APPEL ET AL.: 'Virtual memory primitives for user programs' see page 100, right column, line 12 - line 42 ---	1
<p>¹⁰ Special categories of cited documents:</p> <p>"A" document defining the general state of the art which is not considered to be of particular relevance</p> <p>"E" earlier document but published on or after the international filing date</p> <p>"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)</p> <p>"O" document referring to an oral disclosure, use, exhibition or other means</p> <p>"P" document published prior to the international filing date but later than the priority date claimed</p> <p>"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention</p> <p>"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step</p> <p>"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.</p> <p>"&" document member of the same patent family</p>		
IV. CERTIFICATION		
Date of the Actual Completion of the International Search		Date of Mailing of this International Search Report
11 SEPTEMBER 1992		01. 10. 92
International Searching Authority EUROPEAN PATENT OFFICE		Signature of Authorized Officer LEDROT D. 

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US 9202364
SA 60263

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